On Board Diagnostics II

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OVERVIEW OF ON-BOARD DIAGNOSTICS (OBD I & III)

- In continuing efforts to improve air quality, the Environmental Protection Agency (EPA) amended the Clean Air Act in 1990. The Clean Air Act was originally mandated in 1970. The Clean Air Act has a direct impact on automobile manufactures whereby they are responsible to comply with the regulations set forth by the EPA. The 1990 amendment of the Clean Air Act set forth all of the changes currently being introduced on vehicles sold in the United States today.
- In 1967, the State of California formed the California Air Resources Board (CARB) to develop and carryout air quality improvement programs for California's unique air pollution conditions. Through the years, CARB programs have evolved into what we now know as ON Board Diagnostics (OBD) and the National Low Emission Vehicle Program.
- The EPA has adopted many of the CARB programs as National programs and laws. One of these earlier programs was OBD I and the introduction of the "CHECK ENGINE" Light.
- BMW first introduced OBD I and the check engine light in the 1987 model year. This enhanced diagnosis through the display of "flash codes" using the check engine light as well as the BMW 2013 and MoDiC. OBD I was only the first step in an ongoing effort to monitor and reduce tailpipe emissions.



- By the 1989 model year all automotive manufactures had to assure that all individual components influencing the composition of exhaust emissions would be electrically monitored and that the driver be informed whenever such a component failed.
- Since the 1996 model year all vehicles must comply with OBD II requirements. OBD II requires the monitoring of virtually every component that can affect the emission performance of a vehicle plus store the associated fault code and condition in memory.

If a problem is detected and then re-detected during a later drive cycle more than one time, the OBD II system must also illuminate the Check Engine Light in the instrument cluster to alert the driver that a malfunction has occurred. However, the flash code function of the Check Engine Light in OBD I vehicles is not a function in OBD II vehicles.

• This requirement is carried out by the Engine Control Module (ECM/DME) as well as the Automatic Transmission Control Module (EGS/AGS) and the Electronic Throttle Control Module (EML) to monitor and store faults associated with all components/systems that can influence exhaust and evaporative emissions.

OVERVIEW OF THE NATIONAL LOW EMISSION VEHICLE PROGRAM

Emission Reduction Stages:

While OBD II has the function of monitoring for emission related faults and alerting the operator of the vehicle, the National Low Emission Vehicle Program requires a certain number of vehicles produced (specific to manufacturing totals) currently comply with the following emission stages;

TLEV: Transitional Low Emission Vehicle

LEV: Low Emission Vehicle

ULEV: Ultra Low Emission Vehicle.

Prior to the National Low Emission Vehicle Program, the most stringent exhaust reduction compliancy is what is known internally within BMW as HC II. The benefit of exhaust emission reductions that the National Low Emission Vehicle Program provides compared with the HC II standard is as follows:

	Grams/	/Mile - "New"		I FV-	70
Compliance Level	NMHC Non Methane Hydrocarbon	CO Carbon Monoxide	NOx Oxide(s) of Nitrogen	ULEV-	- 84
TLEV	0.250	3.4	0.4		
LEV	0.131	3.4	0.2		
ULEV	0.040	1.7	0.2		

	Grams/Mile	e at 50,000 miles	3
Compliance	NMHC	CO	NOx
Level	Non Methane Hydrocarbon	Carbon Monoxide	Oxide(s) of Nitrogen
TLEV	0.125	3.4	0.4
LEV	0.075	3.4	0.2
ULEV	0.040	1.7	0.2

Cold Engine Startup - 50° F

	Grams/Mile	e at 100,000 mile	S
Compliance	NMHC	CO	NOx
Level	Non Methane	Carbon Monoxide	Oxide(s) of Nitrogen
	Hydrocarbon		
TLEV	0.156	4.2	0.6
LEV	0.090	4.2	0.3
ULEV	0.055	2.1	0.3

TLEV- 50% cleaner.

EV- 70% cleaner.

JLEV- 84% cleaner.



OBD-II FUNCTION: DRIVING CYCLE

As defined within CARB mail-out 1968.1:

"Trip" is defined as vehicle operation (following an engine-off period) of duration and driving style so that all components and systems are monitored at least once by the diagnostic system except catalyst efficiency or evaporative system monitoring. This definition is subject to the limitations that the manufacturer-defined trip monitoring conditions are all monitored at least once during the first engine start portion of the Federal Test Procedure (FTP).

Within this text the term **"customer driving cycle"** will be used and is defined as engine start-up, operation of vehicle (dependent upon customer drive style) and engine shut-off.

FEDERAL TEST PROCEDURE (FTP)

The Federal Test Procedure (FTP) is a **specific driving cycle** that is utilized by the EPA to test light duty vehicles and light duty truck emissions. As part of the procedure for a vehicle manufacturer to obtain emission certification for a particular model/engine family the manufacturer must demonstrate that the vehicle(s) can pass the FTP defined driving cycle **two consecutive times** while monitoring various components/systems.

Some of the components/systems must be monitored *either once per driving cycle or con-tinuously.*

- 1. Components/systems required to be monitored **once within one driving cycle**:
- Oxygen Sensors
- Secondary Air Injection System
- Catalyst Efficiency
- Evaporative Vapor Recovery System

<u>NOTE</u>: Due to the complexity involved in meeting the test criteria within the FTP defined driving cycle, all tests may not be completed within one "customer driving cycle". The test can be successfully completed within the FTP defined criteria, however customer driving styles may differ and therefore may not always monitor all involved components/systems in one "trip".

Components/systems required to be monitored *continuously*:

- Misfire Detection
- Fuel system
- Oxygen Sensors
- All emissions related components/systems providing or getting electrical connections

to the DME, EGS, or EML.

The graph shown below is an *example* of the driving cycle that is used by BMW to complete the FTP.



The diagnostic routine shown above will be discontinued whenever:

- Engine speed exceeds 3000 RPM
- Large fluctuations in throttle angle
- Road speed exceeds 60 MPH

NOTE: The driving criteria shown can be completed within the FTP required ~11 miles in a controlled environment such as a dyno test or test track.

A "customer driving cycle" may vary according to traffic patterns, route selection and distance traveled, which may not allow the "diagnostic trip" to be fully completed each time the vehicle is operated.

OBD II FUNCTION: "CHECK ENGINE" (MIL) LIGHT

In conjunction with the CARB/OBD II regulations "CHECK ENGINE" light (also referred to as the Malfunction Indicator Light - MIL) is to be illuminated under the following conditions:



- Upon the completion of the second consecutive driving cycle where the previously faulted system is monitored again and the emissions relevant fault is again present.
- Immediately if a catalyst damaging fault occurs (see Misfire Detection).

The illumination of the check engine light is performed in accordance with the Federal Test Procedure (FTP) which requires the lamp to be illuminated when:

- A malfunction of a component that can affect the emission performance of the vehicle occurs and causes emissions to exceed 1.5 times the standards required by the (FTP).
- Manufacturer-defined specifications are exceeded.
- An implausible input signal is generated.
- Catalyst deterioration causes HC-emissions to exceed a limit equivalent to 1.5 times the standard (FTP).
- Misfire faults occur.
- A leak is detected in the evaporative system
- The oxygen sensors observe no purge flow from the purge valve/evaporative system.
- Engine control module fails to enter closed-loop operation within a specified time interval.
- Engine control or automatic transmission control enters a "limp home" operating mode.
- Key is in the "ignition" on position before cranking (Bulb Check Function).

Within the BMW system the illumination of the check engine light is performed in accordance with the regulations set forth in CARB mail-out 1968.1 and as demonstrated via the Federal Test Procedure (FTP).

The following information provides several examples of when and how the "Check Engine" Light is illuminated based on the "customer drive cycle" (DC):

	Т	'RIP i	# 1	Т	'RIP i	# 2	Т	RIP	# 3	Т	'RIP i	# 4	Т	'RIP i	# 5		* Т	RIP	# 43
TEXT NO.	FUNCTION	FAULT CODE SET	MIL STATUS CHECK ENGINE		FUNCTION	FAULT CODE ERASED	MIL STATUS CHECK ENGINE												
1.	YES	YES	OFF															Τ	
2.	YES	YES	OFF	YES	YES	ON													
3.	YES	YES	OFF	NO	NO	OFF	YES	YES	ON										
4.	YES	YES	OFF	YES	NO	OFF	YES	NO	OFF	YES	YES	OFF	YES	YES	ON	Ì			
5.	YES	YES	OFF	YES	YES	ON	YES	NO	ON	YES	NO	ON	YES	NO	OFF				,
6.	YES	YES	OFF	YES	YES	ON	YES	NO	ON	YES	NO	ON	YES	NO	OFF		YES	FAULT CODE ERASEC	OFF

1. A fault code is stored within the respective control module upon the first occurrence of a fault in the system being checked.

2. The "Check Engine" (MIL) light will not be illuminated until the completion of the second consecutive "customer driving cycle" where the previously faulted system is again monitored and a fault is still present or a catalyst damaging fault has occurred.

3. If the second drive cycle was not complete and the specific function was not checked as shown in the example, the engine control module counts the third drive cycle as the "next consecutive" drive cycle. The check engine light is illuminated if the function is checked and the fault is still present.

4. If there is an intermittent fault present and does not cause a fault to be set through multiple drive cycles, two *complete* consecutive drive cycles with the fault present are required for the Check Engine light to be illuminated.

5. Once the "Check Engine" light is illuminated it will remain illuminated unless the specific function has been checked without fault through three complete consecutive drive cycles.

6. The fault code will also be cleared from memory automatically if the specific function is checked through 40* consecutive drive cycles without the fault being detected or with the use of either the DIS, MODIC or Scan tool.

* **NOTE:** In order to clear a catalyst damaging fault (see Misfire Detection) from memory, the condition under which the fault occurred must be evaluated for 80 consecutive cycles without the fault reoccurring.

With the use of a universal scan tool, connected to the "OBD" DLC an SAE standardized DTC can be obtained, along with the **condition associated** with the illumination of the "Check Engine" light.

Using the DIS or MODIC, a fault code and the conditions associated with its setting **can be obtained prior to the illumination of the "Check Engine" light.**

OBD II Diagnostic Trouble Codes (DTC)

The Society of Automotive Engineers (SAE) established the Diagnostic Trouble Codes used for OBD II systems (SAE J2012). The DTC's are designed to be identified by their alpha/ numeric structure. The SAE has designated the emission related DTC's to start with the letter "P" for Powertrain related systems, hence their *nickname* "P-code".



- DTC's are stored whenever the Check Engine Light (MIL) is illuminated.
- A requirement of CARB/EPA is providing universal diagnostic access to DTC's via a standardized Diagnostic Link Connector (DLC) using a standardized tester (scan tool).
- DTC's only provide one set of environmental operating conditions when a fault is stored. This single "Freeze Frame" or snapshot refers to a block of the vehicles environmental conditions for a specific time when the fault first occured. The information which is stored is defined by SAE and is limited in scope. This information may not even be specific to the type of fault.

DTC Storage:

The table represents the stored information that would be available via an aftermarket scan tool if the same fault occurred 5 times

Bosch Systems	Aftermarket Scan Tool
initial fault	SAE defined freeze frame conditions
2 nd occurrence	n/a
3 rd occurrence	n/a
last occurrence	n/a
Siemens Systems	Aftermarket Scan Tool
initial fault	SAE defined freeze frame conditions

Scan Tool Connection:

Starting with the 1995 750 iL and soon after on all 1996 model year BMW vehicles, a separate OBD II Diagnostic Link Connector (DLC) was added.

The DLC provides access for an aftermarket scan tool to test emission related control systems (DME/AGS/EGS and EML). This diagnostic communication link uses the existing TXD II circuit in the vehicle through a separate circuit on the DLC when the 20 pin cap is installed.



BMW Fault Code (DIS/MoDiC)

- BMW Codes are stored as soon as they occur even before the Check Engine Light (MIL) comes on.
- BMW Codes are defined by BMW, Bosch, and Siemens Engineers to provide greater detail to fault specific information.
- Siemens system (1) SET OF (4) fault specific environmental conditions are stored with the first fault occurence. This information can change and is specific to each fault code to aid in diagnosing. A maximum of (10) different faults containing (4) environmental conditions can be stored.
- Bosch systems- a maximum of (4) sets of (3) fault specific environmental conditions are stored within each fault code. This information can change and is specific to each fault code to aid in diagnosing. A maximum of (10) different faults containing (3) environmental conditions can be stored.
- BMW Codes alSO store and display a "time stamp" when the fault last occurred.
- A fault qualifier gives more specific detailed information about the type of fault (upper limit, lower limit, disconnection, plausibility, etc.).
- BMW Fault Codes will alert the technician of the current fault status. He will be advised if the fault is actually still present, not currently present or intermittent. The fault specific information is stored and accessible through DIS or MoDiC.
- BMW Fault Codes determine the diagnostic output for BMW DIS and MoDiC.

BMW Fault Code Storage:

The table below represents the information that would be available via the DIS tester if the same fault occurred 5 times.

Bosch Systems	DIS Tester Information
initial fault	3 fault specific environmental conditions with time stamp, counter, and if fault is currently present or intermittent
2nd occurence	3 fault specific environmental conditions with time stamp, counter, and if fault is currently present or intermittent
3rd occurence	3 fault specific environmental conditions with time stamp, counter, and if fault is currently present or intermittent
last occurence	3 fault specific environmental conditions with time stamp, counter, and if fault is currently present or intermittent
Siemens Systems	DIS Tester Information
initial fault	4 fault specific environmental conditions with time stamp, counter, and if fault is currently present or intermittent

Print Change End BMW Diagnosis DIAGNOSIS	Services REQUESTS		Help
115 Hot-film air mass f Current type of Voltage Value The fault is not curren Detected 5	low		
First fault detection Engine speed Coolant temperature Throttle-valve angle	0h 24min ago 600 rpm 71 C 4 degreee		
Second fault detection Engine speed Coolant temperature Throttle valve angle	0h Omin ago 640 94 4.5		Quick test
Function Selection Document Test	edule	System	

Print Change End Services		Help
BMW Diagnosis DIAGNOSIS REQUESTSThird fault recognition before 0h 6min at:Engine speed680		
Coolant temperature 94 Throttle-valve angle 4.5 degree		
Last fault detection Oh 6min ago Engine speed 560 rpm Coolant temperature 94 C Throttle valve angle 5.5 degree		
	\bigtriangledown	Quick test
Function Selection Document Schedule	System	

BMW Diagnosis FAULTS	[
<pre>1 Throttle valve 1 potentiometer 1, voltage too low (OBDII code P1543)</pre>		
Cause of fault in the electronics of throttle valve 1 or associated wires and connectors: Wiper voltage of pot. 1 in TV1 falls below the minimum permissible value of 0.20 V		
Stored as the 3th fault in the fault memory Short circuit to earth Open circuit Fault constantly present Fault occurred 1 times		
US only: fault lamp (Check Engine) is not being activated by the EMLIIIS control unit		
US only: OBDII code P1543 is at this moment neither stored, nor can it be read out		Note #

E38 shown

Emission Control Function Monitoring & Comprehensive Component Monitoring

OBD II regulations are based on section 1968. 1 of Title 13, California Code of Regulations (CCR), The law set forth in section 1968.1 requires an increase scope of monitoring emission related control functions including:

- Catalyst Monitoring
- Heated Catalyst Monitoring (not currently used on BMW vehicles)
- Misfire Monitoring
- Evaporative System Monitoring
- Secondary Air System Monitoring
- Air Conditioning System Refrigerant Monitoring (Not applicable for BMW vehicles)
- Fuel System Monitoring
- Oxygen Sensor Monitoring
- Exhaust Gas Recirculation (EGR) System Monitoring (Not applicable for BMW vehicles)
- Positive Crankcase Ventilation (PCV) System Monitoring (Not required at this time).
- Thermostat Monitoring (Not required at this time)

Monitoring these emission requirements is a function of the engine control module which uses "data sets" while monitoring the conditions of the environment and the operation of the engine using existing input sensors and output actuators.

The data sets are programmed reference values the engine control module refers to when a specific monitoring procedure is occuring. If the control module cannot determine the environmental and/or engine operating conditions due to an impaired or missing signal, it will set a fault and illuminate the Check Engine Light as described on page 9.

This input or control signal monitoring falls under another category called *"Comprehensive Component Monitoring"*.

The control module must recognize the loss or impairment of the signal or component. It determines a faulted signal or sensor via three conditions:

- 1. Signal or component shorted to ground.
- 2. Signal or component shorted to B+
- 3. Signal or component *lost* (open circuit)

Specific fault codes are used to alert the diagnostician of these conditions.

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Explanation	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Aci<2A).	The DME initiates the secondary ignition for each cylinder then looks for the feedback through the shunt resistor in the harness to determine if the ignition actually occurred.	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>The DME initiates the secondary ignition for each cylinder then looks for the feedback through the shunt resistor in the harness to determine if the ignition actually occurred.</td><td>Within a predetermined time the LDP read switch signal has to change from high to low or from low to high or LDP read switch is "low" for longer then the predetermined time.</td><td>The DME initiates the secondary ignition for each cylinder then looks for th feedback through the shunt resistor in the harness to determine if the ignition actually occurred.</td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Aci<2A).</td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected come. occurs (0.02A-i<2A).</td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A-i<2A).</td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output iransistor and the connected comp. occurs (0.02A-i<2A).</td><td>The CAN message was not received within the expected time</td><td>Failed the Signal Range check against predefined diagnostic limits</td><td>viistire fault was recorded while the low fuel / reserve light in the instrumen sluster was illuminated.</td></i<2a).<>	The DME initiates the secondary ignition for each cylinder then looks for the feedback through the shunt resistor in the harness to determine if the ignition actually occurred.	Within a predetermined time the LDP read switch signal has to change from high to low or from low to high or LDP read switch is "low" for longer then the predetermined time.	The DME initiates the secondary ignition for each cylinder then looks for th feedback through the shunt resistor in the harness to determine if the ignition actually occurred.	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Aci<2A).	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected come. occurs (0.02A-i<2A).	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A-i<2A).	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output iransistor and the connected comp. occurs (0.02A-i<2A).	The CAN message was not received within the expected time	Failed the Signal Range check against predefined diagnostic limits	viistire fault was recorded while the low fuel / reserve light in the instrumen sluster was illuminated.
Input /Output	гоь	Ignition Shunt Resistor	Running losses -valve	Ignition Shunt Resistor	LDP reed contact switch	Ignition Shunt Resistor	O2 Sensor	Injector	02 Sensor	Injector	Instrument Cluster	temperature sensor on radiator outlet	Calculated
- Signal Type - Signal Range - Detection of	Output digital on/off (active low)	Input analog 100 mV Timing	Output digital pulse width (active low)	Input analog 100 mV Timing	Input digital 12V on/off	Input analog 100 mV Timing	Output digital pulse wi dt h (active low)	Output digital oulse width (active low)	Jutput digital pulse width active low)	Dutput digital pulse width active low)	input digital 0-12V binary information	Input analog 12V voltage	DME internal Values ogical
OBD II Requirement / type of test	Final stage Check	Ignition Feedback	Final stage Check	Ignition Feedback	EVAP Monitoring	ignition Feedback	Final stage Check	Final stage Check	Final stage Check	Final stage Check	Timing Check	Signal Range Check	Aisfire Monitoring
Fault Type and Function	M62M73MY98 only: EVAP: LDP Valve - Final Stage	Ignition Coil Oyl. 2	Running losses valve - Final stage	Ignition Coil Cyl. 4	M62M73MY98 only: EVAP: Reed Switch not closed, doesn't open or doesn't close	Ignition Coil Cyl. 6	O2-Sensor-Heater, Post Cat.(Bank2), Insufficient Heating.	Injector Circuit Cylinder 2	O2 Sensor Heater, Pre Cat.(Bank2), insufficient.	Injector Circuit Oylinder 1	M62/M73MY98 only: CAN-Timeout Instrument Cluster	M62M73MY98 only: Engine coolant temperature, radiator outlet	Misfire with low fuel detected
а ра с ра с ра с ра с ра с	- 2	- 5	8 2	202	303	е 8	4 6	5 05	82 22 02	9 90 90	9 00	7 07	88
162 M7	×		×		×		×		×		×	×	×
¥ 25	×		×		×		×		×		×		×
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M44	M52	M62	2 M73	노월 호	Fault Type and Function	OBD II Requirement / type of test	Signal Type - Signal Range - Detection of	Input /Output	Explanation	Remark
					Mass of Volumo Air Flour Circuit	Cinnol Donco Charle				
	×			8 8	Mass of vourie All Flow Orcurt, Range/Perf.	ognar nange oneck	Inpur analog 0-5V voltage	Σ L	raied the Signal Hange check against predefined diagnostic limits	
×		×	×	0 Q	O2 Sensor Pre Cat. (Bank1)	02-Sensor Check	Input anakog 0-1V (high is rich)	02 Sensor	The oxygen sensor signal range is checked to determine if electrical shorts exist on the input line.	Detailed in OBD II training
	×			₽§	Engine Coolant Temp, Circuit Range/Perf.	Signal Range Check	Input analog 0-5V voltage	Coolant Temp sensor	Signal Range is checked against the predefined diagnostic limits.	D
	×			11 11 11 11	EVAP System, Pressure Sensor, Range and Performance.	EVAP Monitoring	Input analog 0-5V vottage	Tank pressure sensor	Signal Range is checked against predefined diagnostic limits	detailed in OBD II training
×		×	×	5 J	O2 Sensor Post Cat.(Bank1)	O2-Sensor Check	Input analog 0-1V (high is rich)	02 Sensor	The oxygen sensor signal range is checked to determine if electrical shorts exist on the input line.	Detailed in OBD II training
	×			5 3 8	Throttle Position Sensor	Rationality Check	Input analog 0-5V voltage	Throttle position sensor	Signal Range is checked against the predetermined diagnostic limits. A ault will set if the Air Flow meter value (volume) does not logically match hrottle position sensor value (throttle opening).	
×		×	×	13 0D	O2 Sensor Heater Circuit Pre Cat (Bank1)	Final stage Check	Output digital (pulse width (active low)	02 Sensor	The final stage inside the DME will set an internal flag whenever a short to pround, a short to battery voltage or a disconnection between the output ransistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>detailed in OBD II training</td></i<2a).<>	detailed in OBD II training
×		×	×	14 0E	O2-Sensor-Heater, Post Cat. (Bank1), insufficient.	Final stage Check	Output digital pulse width (active low)	02 Sensor	The final stage inside the DME will set an internal flag whenever a short to pround, a short to battery voltage or a disconnection between the output ransistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>detailed in OBD II training</td></i<2a).<>	detailed in OBD II training
	×			5 1 2	Intake Air Temperature Range/Performance	Signal Range Check	Input analog 1 0-5V 7 voltage s	Intake Temp sensor	signal Range is checked against predefined diagnostic limits	
×		×	×	15 0F	O2 Sensor Pre Cat. (Bank1), Slow Response time	02-Sensor Check	Input analog 0-1V (high is rich)	02 Sensor	Checks the amount of time the oxygen sensor stays in its rich or lean state. I it remains too long in either rich or lean condition, the fault will set.	detailed in OBD II training
×		×	×	16 10	O2-Sensor Pre Cat (Bank 1)	O2-Sensor Check	Input analog 0-1V (high is rich)	02 Sensor	Checks the amount of time the oxygen sensor takes to switch from rich to keen and vice versa. If it takes too long to switch the fault will set.	detailed in OBD II training
	×			16 10	AC Compressor Pulse Width Signal (E-39 only)	Timing Check	Input digital D-12V oulse width	HKA	lausibility Check of pulse width modulation of the square wave signal equency and if it's permanently high or low.	
×		×	×	1 4	O2 Sensor Post Cat. (Bank1), Slow Response time	O2-Sensor Check (Input analog -1V 'high is rich)	D2 Sensor (Checks the amount of time the oxygen sensor stays in its rich or lean state. It remains too long in either the rich or the lean condition, the fault will set the terment of the termeter the rich or the lean condition.	detailed in OBD II training

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44 4	4 M52	M6	32 M75	pê dê .	c Fault Type and Function	OBD II Requirement / type of test	- Signal Type - Signal Range - Detection of	Input /Output	Explanation	Remark
L				╞						
	×			12 18	EWS Signal not present or faulty	DME HW Test SIO	Input binary stream 0-12V Bit information	EWS	During the time out check no signal was present within the specific time or aulty information from serial interface (parity, overrun, etc.)	
		×	×	8	O2 Sensor Pre Cat. (Bank2)	02-Sensor Check	Input analog 0-1V	O2 Sensor	The oxygen sensor signal range is checked to determine if electrical shorts axist on the input line.	detailed in OBD II
	┦			2			(nign is rich)			training
			×	19	M73LEVMY99 only: CAN Signal, Timeout EKAT	Timing Check	input digital 0-12V	ECU for electrically	The CAN message was not received within the expected time	
				₽ ₽			binary information	heated Catalyst		
	×			8	Check Engine Light, final stage Malfunction	Final stage Check	Output digital steadv	Instrument Cluster	The final stage inside the DME will set an internal flag whenever a short to around, a short to battert voltage or a disconnection between the output	
		_		4			(active low)		ransistor and the connected comp. occurs (0.02A <i<2a).< td=""><td></td></i<2a).<>	
		×	×	8	02 Sensor Post Cat. (Bank2)	O2-Sensor Check	Input analog	O2 Sensor	The oxygen sensor signal range is checked to determine if electrical shorts axist on the input line	detailed in
		:		14			(high is rich)			UBU II training
	×			2	VANOS electrical fault, Malfunction	Final stage Check	Output digital on/off	VANOS valve	The final stage inside the DME will set an internal flag whenever a short to pround, a short to bathery voltage or a disconnection between the orthur)
	-			15			(active low)	-	ransistor and the connected comp. occurs (0.02A <i<2a).< td=""><td></td></i<2a).<>	
		×	×	2	O2 Sensor Pre Cat. (Bank2) Slow Resnonse time	O2-Sensor Check	Input analog	02 Sensor	checks the amount of time the oxygen sensor stays in its rich or lean state.	detailed in
	\square			15			(high is rich)			UBU II training
	×			ង	Injector Circuit Cylinder 3, Malfunction	Final stage Check	Output digital	Injector	The final stage inside the DME will set an internal flag whenever a short to mound, a short to battlery voltage or a disconnection between the output	
				9			(active low)		arisisiur aru tire curineciea comp. occurs (U.UZA <i<za).< td=""><td></td></i<za).<>	
		×	×	8	O2-Sensor Pre Cat (Bank 2)	02-Sensor Check	Input analog 0-1V Mich io dich)	02 Sensor	thecks the amount of time the oxygen sensor takes to switch from rich to the and vice verse. If it takes too long to switch the fault will set.	detailed in OBD II
				₽	Injector Circuit Cylinder 6	Final stane Check	Outhurt dicital	Diactor	he final starse inside the DME will not an interest fire at the test.	training
	×			R !	Malfunction	0	pulse width		round, a short to batter your goor an international wire revert a short to round, a short to batter your goor a disconnection between the output ansister and the connected come course (0.00 Å i 200).	
	\downarrow			-	20 Source Boot Cot (Bool/2) Slaur		(active low)			
		×	×	ß	Response time		nput analog	02 Sensor C	hecks the amount of time the oxygen sensor stays in its rich or lean state. It remains too long in either the rich or the lean condition, the fault will set (detailed in OBD II
				4			(high is rich)			training
	×			24	Injector Circuit Cylinder 4, Malfunction	Final stage Check	Dutput digital	njector 1	he final stage inside the DME will set an internal flag whenever a short to round, a short to battery voltage or a disconnection between the output	
				₽			active low)		ansistor and the connected comp. occurs (0.02A <i<2a).< td=""><td></td></i<2a).<>	
×		×	×	24	AC Compressor Function	Rationality Check	nput digital	HKA	ault will set if AC-Switch is off and Compressor Switch is on.	
1		;	!	18			in/off			

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DME: MS41.1 (Siemens), M5.2 (Bosch), M5.2.1 (Bosch) Engines: M44, M52, S52, M52ORVR, M62, M62MJ98, M73, M73MJ98

			- T	_	-		_	_						-		_			_						
Remark	detailed in	OBD II training	detailed in OBD II	training		detailed in	OBD II Training	detailed in	OBD II Training	D															
Explanation	The final stage inside the DME will set an internal flag whenever a short to k	ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A⊲i<2A).	Range control of adaptation values		The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Aci<2A).	Range control of adaptation values	~ =	Range control of adaptation values		The final stage inside the DME will set an internal flag whenever a short to protinct a short to battaor voltana or a disconnection between the output	transistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>The DME initiates the secondary ignition for each cylinder then looks for the feedback through the shunt resistor in the harness to determine if the</td><td>ignition actually occurred.</td><td>not applied yet - future enhancement for MY99</td><td></td><td>The DME initiates the secondary ignition for each cylinder then looks for the feedback through the shurt resistor in the harness to determine if the</td><td>ignition actually occurred.</td><td>The DME initiates the secondary ignition for each cylinder then looks for the feedback through the shurt resistor in the harness to determine if the</td><td>ignition actually occurred.</td><td>Plausibility check between the actual engine speed and the predetermined engine speed. Fault will set if not within the desired RPM range ($\pm 200^{-1}00$</td><td>(mdr</td><td>not applied yet - future enhancement for MY99</td><td></td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output</td><td>transistor and the connected comp. occurs (0.02A<i<2a).< td=""></i<2a).<></td></i<2a).<>	The DME initiates the secondary ignition for each cylinder then looks for the feedback through the shunt resistor in the harness to determine if the	ignition actually occurred.	not applied yet - future enhancement for MY99		The DME initiates the secondary ignition for each cylinder then looks for the feedback through the shurt resistor in the harness to determine if the	ignition actually occurred.	The DME initiates the secondary ignition for each cylinder then looks for the feedback through the shurt resistor in the harness to determine if the	ignition actually occurred.	Plausibility check between the actual engine speed and the predetermined engine speed. Fault will set if not within the desired RPM range ($\pm 200^{-1}00$	(mdr	not applied yet - future enhancement for MY99		The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output	transistor and the connected comp. occurs (0.02A <i<2a).< td=""></i<2a).<>
Input /Output	02 Sensor		Calculated		Idle control valve	Calculated		Calculated		air containment		Ignition Shunt Resistor		EKAT-ECU	_	Ignition Shunt Besistor		Ignition Shunt Besistor		Idie control Valve		EKAT-ECU		Injector	
- Signal Type - Signal Range - Detection of	Output digital	pulse width (active low)	DME internal Values	logical	Output digital pulse width, 120Hz (active low)	DME internal Values	logical	DME internal Values	logical	Output digital	(active low)	Input analog 100 mV	Timing	input digital 0-12V	binary information	Input analog	Timing	nput analog	Timing	DME internal Values	ogical	Input digital 2-12V	binary information	Dutput digital ulse width	active low)
OBD II Requirement / type of test	Final stage Check		Fuel System Monitoring		Final stage Check	Fuel System Monitoring		Fuel System Monitoring		Final stage Check	_	Ignition Feedback		Electrically heated	_	I tignition Feedback		gnition Feedback		Plausibility Check	<u>×</u>	Electrically heated		Final stage Check C	<u> </u>
Fault Type and Function	02 Sensor Heater Circuit Pre Cat		Fuel Trim at part load (Bank1), Multiplicative		Idle Control Valve Closing Coil, Malfunction	Fuel Adaptation Additive at idle		Fuel Trim (Bank1), Additive		M62/M73MY98 only: air containment valve for air control of	shrouded fuel injector (Bank 1)	Ignition Coil Cyl. 1		M73LEVMY99 only: EKAT-Status 7 - power switch control		Ignition Coil Cyl. 3		Ignition Coil Cyl. 5		Idle Control Valve stuck	•	M73LEVMY99 only: EKAT-Status 81		Injector Circuit Cylinder 5, F Malfunction	
73 dei hey	25	19	56	4	27 1B	2	9 9	88	9	59	<u>9</u>	53	₽	30	Ħ	8	Ħ	31	1F	32	20	33	2	33	5
M62 M.	-	-	×	-	·	`	< <	`	< <	×				×						×		×	_		
M52	>	<		-	×	\vdash		F	-		-	×				×	_	×						×	
M44			×	-†		>	<	>	<				┤						_	×					_
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	Remark		detailed in	OBD II training	R		detailed in	OBD II training	detailed in	OBD II Iraining	R		detailed in	JBD II raining	þ						letailed in	7810 II raining	,					
	Explanation		Range control of adaptation values		The final stage inside the DME will set an internal flag whenever a short to coround, a short to battery voltage or a disconnection between the output	transistor and the connected comp. Occurs (0.024 24).</td <td>Range control of adaptation values</td> <td></td> <td>Range control of adaptation values</td> <td>~ .</td> <td>The content of the binary message received from EWS was invalid</td> <td></td> <td>Compares the value of the of pre cat O2 sensor to value of the post cat O2 kensor to measure the overcas stream container / afficiency of the overcas</td> <td>converter. The post O2 sensor must be relatively learn.</td> <td>not applied yet - future enhancement for MY99</td> <td></td> <td>not applied yet - future enhancement for MY99</td> <td></td> <td>not applied yet - future enhancement for MY99</td> <td></td> <td>Compares the value of the of pre cat O2 sensor to value of the post cat O2 c sensor to measure the overean storage canability / officiancy of the catability /</td> <td>consort or increased a tric oxygen; severage capacity if an increasing a many in the many in the many in the post O2 sensor must be relatively lean.</td> <td>tot applied yet - future enhancement for MY99</td> <td></td> <td>tot applied yet - future enhancement for MY99</td> <td></td> <td>tot applied yet - future enhancement for MY99</td> <td></td>	Range control of adaptation values		Range control of adaptation values	~ .	The content of the binary message received from EWS was invalid		Compares the value of the of pre cat O2 sensor to value of the post cat O2 kensor to measure the overcas stream container / afficiency of the overcas	converter. The post O2 sensor must be relatively learn.	not applied yet - future enhancement for MY99		not applied yet - future enhancement for MY99		not applied yet - future enhancement for MY99		Compares the value of the of pre cat O2 sensor to value of the post cat O2 c sensor to measure the overean storage canability / officiancy of the catability /	consort or increased a tric oxygen; severage capacity if an increasing a many in the many in the many in the post O2 sensor must be relatively lean.	tot applied yet - future enhancement for MY99		tot applied yet - future enhancement for MY99		tot applied yet - future enhancement for MY99	
	Input /Output		Calculated		Air pump		Calculated		Calculated		EWS		02 Sensor	pre/post catalyst	EKAT-ECU		EKAT-ECU		EKAT-ECU		02 Sensor	pie/post catalyse	EKAT-ECU		EKAT-ECU		EKAT-ECU	
	- Signal Type - Signal Range - Detection of		DME internal Values	logical	Output digital on/off	(active low)	DME internal Values	logical	DME internal Values	logical	Input binary stream	0-12V Bit information	Input analog	voltage	input digital	0-12V binary information	input digital	binary information	input digital 0-12V	binary information	nput analog	voltage	input digital 0-12V	binary information	input digital	oinary information	nput digital 0-12V	oinary information
	OBD II Requirement / type of test		Fuel System Monitoring		Final stage Check		Fuel System Monitoring		Fuel System Monitoring		Manipulation Check		Catalyst Monitoring	e	Electrically heated	catalyst cneck	Electrically heated	alaiysi uracu	Electrically heated catalvst check		Catalyst Monitoring	2.2	Electrically heated		Electrically heated		Electrically heated	
	Fault Type and Function		Fuel Irim (bankz), Muitiplicative		Secondary Air Injection System , el. Pump		Fuel Adaptation Additive at idle /	()	Fuel Trim at part load (Bank2), Iddditive		EWS Content of Message		Catalyst Efficiency Bank 1, Below (Threshold		M73LEVMY99 only: EKAT-Status 1	- Ulsconnection of neater for Catalyst 1	M73LEVMY99 only: EKAT-Status 2	catalyst 1	M73LEVMY99 only: EKAT-Status 3 [- power switch Catalyst 1		Catalyst Efficiency Bank 2, Below C		M73LEVMY99 only: EKAT-Status 4 [2	M73LEVMY99 only: EKAT-Status 5 F	catalyst 2	M73LEVMY99 only: EKAT-Status 6 E - power switch catalyst 2	
1	2 de 2		3	8	35	ស្ត	35	ឌ	36	24	8	27	4	58	4	2A	43	2B	4	SC	45	2D	46	ZE	47	2F	84	8
	162 M7	$\left \right $	×			_	×		×	:	>	<	×	:	>	<	×	(×		×	:	×		×		×	
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		L	Ĺ	Ē						
M44	M52	WG	2 M73	Ê ê	c k Fault Type and Function	OBD II Requirement / type of test	- Signal Type - Signal Range - Detection of	Input /Output	Explanation	Remark
				L	Running Loss Valve (3/2) final stare	Einal stade Chade	D. 41-4 - 11-14-1	-		
	×		_	3 8			ourput argital	HL vave	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output	
				8	Odindor 1 Micfac detected		(active IOW)		interisistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>_</td></i<2a).<>	_
×		×	×	22		Mistire Monitoring	DME internal Values	Calculated	Crankshaft speed/acceleration is monitored by the crank sensor. The time for each cylinders combustion is command accined the accessory of the	detailed in
				8	i		logical		others. If the time for cylinder 1 is longer the fault will set.	0BD II training
	×			51	Shut Off Valve, Malfunction	Final stage Check	Output digital	Shut off valve	The final stage inside the DME will set an internal flag whenever a short to	p
				R			steady (active low)		ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. Occurs (0.02A <i<2a).< td=""><td></td></i<2a).<>	
×		×	×	51	Cylinder 2 Misfire detected	Misfire Monitoring	DME internal Values	Calculated	Crankshaft speed/acceleration is monitored by the crank sensor. The time	detailed in
				R			logical		or each cylinders combustion is compared against the average of the others. If the time for cylinder 2 is longer the fault will set.	OBD II training
	×			22	Rear Exhaust Valve flap	Final stage Check	Output digital	Valve for exhaust	The final stage inside the DME will set an internal flag whenever a short to	R. IIII
	:			34			steady (active low)	flap	ground, a short to battery voltage or a disconnection between the output ransistor and the connected comp. occurs (0.02A⊲i<2A).	
×		×	×	23	Cylinder 3 Misfire detected	Misfire Monitoring	DME internal Values	Calculated	Crankshaft speed/acceleration is monitored by the crank sensor. The time [Detailed in
				8			logical		or each cylinders compuston is compared against the average of the time for cylinder 3 is longer the fault will set.	OBD II training
	×			53	Idle Control Valve Opening Coil, Malfunction	Final stage Check	Output digital	Idle control valve	he final stage inside the DME will set an internal flag whenever a short to	Remon
				35			pulse width, 120Hz (active low)	<u> </u>	round, a short to battery voltage or a disconnection between the output ansistor and the connected comp. occurs (0.02A <i<2a).< td=""><td></td></i<2a).<>	
×		×	×	53	Cylinder 4 Misfire detected	Visfire Monitoring	DME internal Values	Calculated	rankshaft speed/acceleration is monitored by the crank sensor. The time of	detailed in
				35			logical		thers. If the time for cylinder 4 is longer the fault will set.	OBD II
		×	×	54	Cylinder 5 Misfire detected	Misfire Monitoring	DME internal Values	Calculated 6	stankshaft speed/acceleration is monitored by the crank sensor. The time of	detailed in
				g		-	logical	. 0	thers. If the time for cylinder 5 is longer the fault will set.	OBD II training
	×			55	UZ Sensor Heater Circuit Pre Cat	inal stage Check (Output digital	02 Sensor	he final stage inside the DME will set an internal flag whenever a short to d round, a short to battery voltage or a disconnection between the output	detailed in
		1	+	3			(active low)	ţ,	ansistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>raining</td></i<2a).<>	raining
_		×	×	55	Cyllinder 6 Mistire detected	Aisfire Monitoring	OME internal Values C	Calculated C	rankshaft speed/acceleration is monitored by the crank sensor. The time of or each cylinders combustion is command analine the evence of the	Jetailed in
	1			37	-		ogical	ò	thers. If the time for cylinder 6 is longer the fault will set.	raining
	×			56	Ignition Feedback, interruption at II	gnition Feedback	nput analog	gnition Shunt O	heck for correct signal voltage if Voltage is 32V (Zener Voltage) than	,
-†	-†	-†	-+	8		22	/oltage		econtery regiment younge is detected then there might be a problem with e shunt resistor in the hamess.	
		×	×	56	Cylinder 7 Misfire detected	Aisfire Monitoring	DME internal Values C	Calculated C	rankshaft speed/acceleration is monitored by the crank sensor. The time of	letailed in
	-	_	-	88		<u> </u>	ogical	0	reconstructions of the time for cylinder 7 is longer the fault will set.	DBD II

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Rema					trainin		4	detaile	0BD trainin			detaile	OBD	trainin	detaile	OBD			trainin	detaile OBD I	trainin			detaile	OBD	trainin	detaile	UBU I trainin		
Explanation		Haustoniny Check between the knock sensor amplitude during knocking with the internal knock detection mapped DME values.	Crankshaft sneed/acceleration is monitored by the crank sensor. The time	for each cylinders combustion is compared against viam series. The mine for each cylinders combustion is compared against the average of the others: If the time for cylinder 8 is knower the fault will set		Plausibility Check between the knock sensor amplitude during knocking with the internal knock detection mapped DME values.		The final stage inside the DME will set an internal flag whenever a short to	ground, a short to battery voitage or a disconnection between the output transistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>The final stage inside the DME will set an internal flag whenever a short to</td><td>ground, a short to battery voitage or a disconnection between the output transistor and the connected comp. Occurs (0.02A⊲i<2A).</td><td>Crankshaft speed/acceleration is monitored by the crank sensor. The time</td><td>for each cylinders compution is compared against the average of the others. If the time for a cylinder is longer the fault will set</td><td></td><td>Crankshaft speed/acceleration is monitored by the crank sensor. The time</td><td>for each cynnoers computed is compared against the average of the others. If the time for cylinder 1 is longer the fault will set.</td><td>Crankshaft mood/moodscripe is monitored by the second second</td><td>for each cylinders combustion is compared against the average of the</td><td>others. If the time for cylinder 2 is longer the fault will set.</td><td>Crankshaft speed/acceleration is monitored by the crank sensor. The time for each cylinders combustion is compared against the average of the</td><td>others. If the time for cylinder 3 is longer the fault will set.</td><td>Internal check of the phase shift from the cam sensor which should change</td><td>uuring every cramksham revolution. The phase shift occurs due to the 2:1 mechanical relationship between cam and crank.</td><td>Crankshaft speed/acceleration is monitored by the crank sensor. The time</td><td>for each cylinders combustion is compared against the average of the</td><td>others. If the time for cylinder41 is longer the fault will set.</td><td>Crankshaft speed/acceleration is monitored by the crank sensor. The time</td><td>others. If the time for cylinder 5 is longer the fault will set.</td><td>The final stage inside the DME will set an internal flag whenever a short to provind a short to hattery where or a disconnection between the order to</td><td>ground, a short to carrier y runage or a discontinedurit permanent into output, transistor and the connected comp. occurs (0.02A<i<2a).< td=""></i<2a).<></td></i<2a).<>	The final stage inside the DME will set an internal flag whenever a short to	ground, a short to battery voitage or a disconnection between the output transistor and the connected comp. Occurs (0.02A⊲i<2A).	Crankshaft speed/acceleration is monitored by the crank sensor. The time	for each cylinders compution is compared against the average of the others. If the time for a cylinder is longer the fault will set		Crankshaft speed/acceleration is monitored by the crank sensor. The time	for each cynnoers computed is compared against the average of the others. If the time for cylinder 1 is longer the fault will set.	Crankshaft mood/moodscripe is monitored by the second second	for each cylinders combustion is compared against the average of the	others. If the time for cylinder 2 is longer the fault will set.	Crankshaft speed/acceleration is monitored by the crank sensor. The time for each cylinders combustion is compared against the average of the	others. If the time for cylinder 3 is longer the fault will set.	Internal check of the phase shift from the cam sensor which should change	uuring every cramksham revolution. The phase shift occurs due to the 2:1 mechanical relationship between cam and crank.	Crankshaft speed/acceleration is monitored by the crank sensor. The time	for each cylinders combustion is compared against the average of the	others. If the time for cylinder41 is longer the fault will set.	Crankshaft speed/acceleration is monitored by the crank sensor. The time	others. If the time for cylinder 5 is longer the fault will set.	The final stage inside the DME will set an internal flag whenever a short to provind a short to hattery where or a disconnection between the order to	ground, a short to carrier y runage or a discontinedurit permanent into output, transistor and the connected comp. occurs (0.02A <i<2a).< td=""></i<2a).<>
Input /Output	-	Knock sensor	Calculated			Knock sensor		O2 Sensor		Air valve	·	Calculated			Calculated		Calarulated	Calculation		Calculated		CAM sensor		Calculated			Calculated		purge valve	
- Signal Type - Signal Range - Detection of		input analog 13-19kHz amplitude	DMF internal Values		logical	Input analog 13-19kHz	amplitude	Output digital	pulse width (active low)	Output digital	on/off (active low)	DME internal Values	lociool	nogical	DME internal Values	looical	DME internal Values		logical	DME internal Values	logical	input analog	0-5V phase shift	DME internal Values		logical	DME internal Values	logical	Output digital	sleacy (active low)
OBD II Requirement / type of test		orcur continuity Signal Range Check	Misfire Monitoring	0		Circuit continuity Signal Range Check	,	Final stage Check		Final stage Check		Misfire Monitoring			Misfire Monitoring		diefire Monitorina			disfire Monitoring		Rationality Check		Aisfire Monitoring)		Aisfire Monitoring		inal stage Check	
Fault Type and Function	Knock Scanor 1 Cimility (Book 1)		Cvlinder 8 Misfire detected			Knock Sensor 2 Circuit, (Bank 2)		O2 Sensor Heater Circuit Post Cat	(Danke)	Secondary Air Inj. System Switching	valve	Random/Muttiple Cylinder, Misfire	Delecied		Cylinder 1 Misfire detected, catalyst	dar nagir g	Cylinder 2 Mistire detected catalyst	damaging		Cylinder 3 Misfire detected, catalyst 7 damaging		Camshaft Position Sensor Circuit, 1	Mairunction	Cylinder 4 Misfire detected, catalyst 🕅	damaging		Cylinder 5 Misfire detected, catalyst		EVAP System, Purge Control Valve F	
고 영 포		57 39		22	3	59	3B	61	B	8	l Ш	8	Ļ	뜅	8	Ë	5	8	6	65	41	65	41	: ?	8	4	67	£	89	4
M73			L	×	╡							>	<		>	<	\downarrow	×		×					×		>	<		
We		<u> </u>		×								>	<		>	<		×		×					×		>	<		
M52		×				×		>	<	>	×						╞					,	<						>	<
M44												>	<		>	<		×		×					×					
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	Remark		detailed in OBD II	training		dotnical in		training	detailed in	training	detailed in	training	detailed in	OBD II training	detailed in	training			detailed in	training	detailed in	training	detailed in	training	detailed in OBD II	training		
	Explanation		Crankshaft speed/acceleration is monitored by the crank sensor. The time for each orlinders combation is compared against the average of the	others. If the time for cylinder 6 is longer the fault will set.	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Asi/22A).	Crankshaft sneedlaccalaration is monitored by the crank sensor. The time	for each cylinders combustion is compared against the average of the	UNITION. IN UNE UNITE TO CONTRIDER / IS IONGER THE TAUR WILL SET.	Crankshaft speed/acceleration is monitored by the crank sensor. The time for each cylinders combustion is compared against the average of the	others. If the time for cylinder 8 is longer the fault will set.	Crankshaft speed/acceleration is monitored by the crank sensor. The time for each cylinders combustion is compared analysis of the	others. If the time for cylinder 9 is longer the fault will set	Crankshaft speed/acceleration is monitored by the crank sensor. The time	for each cylinders combustion is compared against the average of the others. If the time for cylinder 10 is longer the fault will set.	Crankshaft speed/acceleration is monitored by the crank sensor. The time for each relinders contrinsion is composed and the average of the	others. If the time for cylinder 11 is longer the fault will set.	The final stage inside the DME will set an internal flag whenever a short to printing a short to harbor withons or a disconnection between the output	ground, a short to battery voltage or a discontinection between the output transistor and the connected comp. occurs (0.02A 2A).</td <td>Crankshaft speed/acceleration is monitored by the crank sensor. The time for each colinders combustion is compared analised the automore of the</td> <td>others. If the time for cylinder 12 is longer the fault will set.</td> <td>Crankshaft speed/acceleration is monitored by the crank sensor. The time for each cylinders combustion is compared against the average of the</td> <td>others. If the time for a cylinder is longer the fault will set.</td> <td>The oxygen sensor signal range is checked to determine if electrical shorts exist on the input line. The voltage signal has to be within a predetermined</td> <td>range (0,1V - 4.9V) or a fault will set.</td> <td>The oxygen sensor signal range is checked to determine if electrical shorts exist on the input line. The voltage signal has to be within a predetermined</td> <td>range (0,1V - 4.9V) or a fault will set.</td> <td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output</td> <td>transistor and the connected comp. occurs (0.02A<i<2a).< td=""></i<2a).<></td>	Crankshaft speed/acceleration is monitored by the crank sensor. The time for each colinders combustion is compared analised the automore of the	others. If the time for cylinder 12 is longer the fault will set.	Crankshaft speed/acceleration is monitored by the crank sensor. The time for each cylinders combustion is compared against the average of the	others. If the time for a cylinder is longer the fault will set.	The oxygen sensor signal range is checked to determine if electrical shorts exist on the input line. The voltage signal has to be within a predetermined	range (0,1V - 4.9V) or a fault will set.	The oxygen sensor signal range is checked to determine if electrical shorts exist on the input line. The voltage signal has to be within a predetermined	range (0,1V - 4.9V) or a fault will set.	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output	transistor and the connected comp. occurs (0.02A <i<2a).< td=""></i<2a).<>
	Input /Output		Calculated		Relay fuel pump	Calculated			Calculated		Calculated		Calculated		Calculated		Relay AC	compr.	Calculated		Calculated		O2 Sensor		02 Sensor		air containment valve	
	- Signal Type - Signal Range - Detection of		DME internal Values	logical	Output digital on/off (active low)	DME internal Values	-	logical	DME internal Values	logical	DME internal Values	logical	DME internal Values	logical	DME internal Values	logical	Output digital	active low)	DME internal Values	logical	DME internal Values	ogical	nput analog	high is lean)	nput analog)-5V	high is lean)	Output digital on/off	(active low)
	OBD II Requirement / type of test		Misfire Monitoring		Final stage Check	Mistire Monitorina	D		Misfire Monitoring		Misfire Monitoring		Misfire Monitoring		Misfire Monitoring		-inal stage Check		Misfire Monitoring		Aisfire Monitoring		22-Sensor Check		02-Sensor Check 1	(-inal stage Check	
	Fault Type and Function		Cylinder 6 Misfire detected, catalyst damaging		Relay Fuel Pump	Cylinder 7 Misfire detected, catalyst	damaging		Cylinder 8 Misfire detected, catalyst damaging		Cylinder 9 Misfire detected, catalyst damacing	0	Cylinder 10 Misfire detected,	catalyst damaging	Cylinder 11 Misfire detected,	0	Relay AC Compressor		Cylinder 12 Misfire detected,	8. South to 10	Random/Multiple Cylinder, Misfire		22 Sensor Pre Cat. (Bank1)		02 Sensor Pre Cat. (Bank2)		M62M73MY98 only: air containment valve for air control of	shrouded fuel injector (Bank 2)
2	2 B B B B C B C B C B C B C B C B C B C		89	4	69	2	69	45	20	46	7	47	2	; 8	73	49	74	4A	74	4A	75	4B	75	4B	76	Ą	1	٩ ۲
╞	762 M7		× 	-			× 	+	×		×	{		×	×				×	:	×	:					×	
┝	125	$\left \right $		+	×	╀		+					-				X				×	•		_		_	×	
╞	M44 N	ŀ		+		╀		╉				_	L					-			×			' 		_		
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FC	FC	FC						
dec hex Fault Type and Function	dec Fault Type and Function	dec hex Fault Type and Function	Fault Type and Function	_ o ≥i	BD II Requirement / pe of test	 Signal Type Signal Range Detection of 	Input /Output	Explanation
77 O2 Sensor Post Cat.(Bank1) O2	77 O2 Sensor Post Cat.(Bank1) 02	77 O2 Sensor Post Cat (Bank1) O2	O2 Sensor Post Cat.(Bank1) 02		2-Sensor Check	Input analog	02 Sensor	The oxygen sensor signal range is chec
4D	4D	4D		1		vc-v (high is lean)		exist on the input line. I ne voltage signal has range (0,1V - 4.9V) or a fault will set.
78 O2 Sensor Post Cat. (Bank2) O2-9 4E	78 O2 Sensor Post Cat. (Bank2) O2-9 4E	78 O2 Sensor Post Cat. (Bank2) O2-9 4E	02 Sensor Post Cat. (Bank2) 02-9	N.	Sensor Check	Input analog 0-5V (high is lean)	02 Sensor	The voltage signal has to be within a predetermined a fault will set.
 78 Crankshaft Position Sensor (too Ratii 78 marry teeth) 45 	78 Crankshaft Position Sensor (too Rati 78 many teeth) 4E	78 Crankshaft Position Sensor (too Rati 78 mary teeth) 4E	Crankshaft Position Sensor (too Rati marry teeth)	iti ati	onality Check	Input digital 0-12V frequency/pattern	Crank sensor	Crank sensor signal reports that too many teeth were dete crankshaft revolution. The fault will set if more teeth was default value.
79 (Bank1, Sensor Heater Circuit Fina 4F	79 O2 Sensor Heater Circuit Fina 79 (Bank1,Sensor2) 4F	79 02 Sensor Heater Circuit Fina 79 (Bank1,Sensor2) 4F	O2 Sensor Heater Circuit (Bank1,Sensor2)	1 <u>8</u>	l stage Check	Output digital pulse width (active low)	O2 Sensor	The final stage inside the DME will set an internal flag whene ground, a short to battery voltage or a disconnection betweer transistor and the connected comp. occurs (0.02A <i<2a).< td=""></i<2a).<>
80 Secondary Air Control Se 50	80 Secondary Air Control Se 50	80 Secondary Air Control Secondary Air Control Secondary Air Control	Secondary Air Control Se	A 1	condary Air Delivery	Input analog 0-1V voltage	O2 Sensor	Checks to see if the O2 sensor reacts to the increase in unmet generated by the secondary air pump operation. The O2 sens sense the lean condition or a fault will set.
ASC Signal, active too long 50	80 ASC Signal, active too long Trir 50	80 ASC Signal, active too long Trir 50	ASC Signal, active too long	C .	ning Check	Input digital 0-12V timing	ASC	Time out Check, Fault occurs when ASC signal is active for mor seconds
M73LEVMY99 only: EKAT-Status 9 Ele 81 - sensor check temperature sensor cat 51 (1) in battery	M73LEVMY99 only: EKAT-Status 9 Ele 81 - sensor check temperature sensor cat 51 (1) in battery	M73LEVMY99 only: EKAT-Status 9 Ele 81 - sensor check temperature sensor cat 51 (1) in battery	M73LEVMY99 only: EKAT-Status 9 Ele - sensor check temperature sensor cat (1) in battery	0 <u>5</u> 1	ctrically heated alyst check	input digital 0-12V binary information	EKAT-ECU	not applied yet - future enhancement for MY99
MSR Signal, active too long Tirr 51	81 MSR Signal, active too long Tim 51	81 MSR Signal, active too long Tim 51	MSR Signal, active too long Tirr	F 1	ing Check	Input digital 0-12V timing	ASC	Time out Check, Fault when MSR signal is active for more than 5 $lpha$
M73LEVMY99 only: EKAT-Status Ele 82 10 - sensor check temperature che 52 sensor (2) in battery	M73LEVMY99 only: EKAT-Status Ele. 82 10 - sensor check temperature che 52 sensor (2) in battery	M73LEVMY99 only: EKAT-Status Ele. 82 10 - sensor check temperature che 52 sensor (2) in battery	M73LEVMY99 only: EKAT-Status Ele 10 - sensor check temperature che sensor (2) in battery	õ o	ctrical heated catalyst ck	input digital 0-12V binary information	EKAT-ECU	hot applied yet - future enhancement for MY99
82 EML Signal, active too long Tim 52	82 EML Signal, active too long Tim 52	82 EML Signal, active too long Tim 52	EML Signal, active too long Timi	Έ I	ing Check	Input digital 0-12V timing	ASC	Time out Check, Fault when EML signal is active for more than 5 se
M73LEVMY99 only: EKAT-Status Election 31 11- plausibility check of 33 temperature sensor in battery.	M73LEVMY99 only: EKAT-Status Elec 83 11 - plausibility check of 53 temperature sensor in battery.	M73LEVMY99 only: EKAT-Status Elec 83 11 - plausibility check of 53 temperature sensor in battery.	M73LEVMY99 only: EKAT-Status Election 11 - plausibility check of the temperature sensor in battery.	2 O 0	ctrical heated catalyst ck	Input digital 0-12V binary Information	EKAT-ECU	not applied yet - future enhancement for MY99
Crankshaft Position Sensor, Ratii 83 Malfunction 33	B3 Crankshaft Position Sensor, Rati Malfunction 53	B3 Crankshaft Position Sensor, Rati B3 Malfunction 53	Crankshaft Position Sensor, Malfunction	ið l	onality Check	Input digital 0-12V irequency/pattern	Crank sensor	Checks for correct signal pattern and correct number of expected fly teeth.
 Secondary Air Pump Final stage Final s 54 	84 Secondary Air Pump Final stage Final s	84 Secondary Air Pump Final stage Final s 84	Secondary Air Pump Final stage Final s	als	tage Check	Output digital	Secondary Air oump	The final stage inside the DME will set an internal flag whenever a s ground, a short to battery voltage or a disconnection between the ou ransistor and the connected comp. occurs (0.02Aci<2A).

		1									1	1	<u> </u>	<u> </u>	<u> </u>
	Remark					detailed in OBD II	detailed in OBD II troining		detailed in OBD II training				1		
	Explanation		The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Aci<2A).	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the ourput transistor and the connected comp. occurs (0.02A<!--2A).</td--><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transition and the connected come, occurs () 0.2Asi<</td><td>During purging with the open TEV valve the tank pressure sensor must react to the decrease in pressure. It must reach a minimum pressure differential after a predetermined time or at fault will set.</td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. Occurs (0.024<i22a).< td=""><td>With the purge open and shut off valve closed the gas tank is introduced to intele manifold vacuum. The tank pressure sensor looks for a predetermined pressure (vacuum) difference within a specific time.</td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A<i<2a).< td=""><td>Internal hardware test of RAM, ROM, and Flash Prom.</td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A<i<2a).< td=""><td>Internal hardware test of RAM, ROM, and Flash Prom.</td><td>internal hardware test of RAM, ROM, and Flash Prom.</td><td>nternal hardware test of RAM, ROM, and Flash Prom.</td></i<2a).<></td></i<2a).<></td></i22a).<></td></td></i<2a).<>	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the ourput transistor and the connected comp. occurs (0.02A 2A).</td <td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transition and the connected come, occurs () 0.2Asi<</td> <td>During purging with the open TEV valve the tank pressure sensor must react to the decrease in pressure. 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It must reach a minimum pressure differential after a predetermined time or at fault will set.	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. Occurs (0.024 <i22a).< td=""><td>With the purge open and shut off valve closed the gas tank is introduced to intele manifold vacuum. 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The tank pressure sensor looks for a predetermined pressure (vacuum) difference within a specific time.	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>Internal hardware test of RAM, ROM, and Flash Prom.</td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A<i<2a).< td=""><td>Internal hardware test of RAM, ROM, and Flash Prom.</td><td>internal hardware test of RAM, ROM, and Flash Prom.</td><td>nternal hardware test of RAM, ROM, and Flash Prom.</td></i<2a).<></td></i<2a).<>	Internal hardware test of RAM, ROM, and Flash Prom.	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>Internal hardware test of RAM, ROM, and Flash Prom.</td><td>internal hardware test of RAM, ROM, and Flash Prom.</td><td>nternal hardware test of RAM, ROM, and Flash Prom.</td></i<2a).<>	Internal hardware test of RAM, ROM, and Flash Prom.	internal hardware test of RAM, ROM, and Flash Prom.	nternal hardware test of RAM, ROM, and Flash Prom.
	Input /Output		secondary air pump	Secondary Air valve	purge valve	Tank pressure sensor	Tank pressure sensor	Shut off valve	Tank pressure sensor	purge valve	DME internally	Trans/coolant heat exchanger	DME internally	DME internally	DME internally
	- Signal Type - Signal Range - Detection of		Output digital on/off (active low)	Output digital on/off (active low)	Output digital on/off (active low)	input analog D-5V voltacie	nput analog D-5V voltage	Dutput digital steady active low)	nput analog -5V ottage	Dutput digital n/off active low)	0ME internal Values ogical	Dutput digital on/off active low)	0ME internal Values ogical	ME internal Values ogical	ME internal Values orical
	OBD II Requirement / type of test		Final stage Check	Final stage Check	Final stage Check	EVAP Monitoring	EVAP Monitoring	inal stage Check	EVAP Monitoring	Tinal stage Check	DME HW Test Memory C	-inal stage Check (DME HW Test Memory C	ME HW Test Memory D	ME HW Test Memory D
	Fault Type and Function		M44/M73MY98 only: CDTSLPE: secondary air pump - final stage	Secondary Air Valve Final stage	M62M73MY98 only: EVAP System, Purge Control Valve Circuit (Bank 2)	EVAP Emission Control System	EVAP System Large Leak	Shut Off Valve, Malfunction	EVAP System Small Leak detected t	EVAP System, Purge Control Valve ^I Circuit	Internal Control Module, Memory [check sum or internal communication	M73LEV only: Transmission/ coolant heat exchanger	Internal Control Module, RAM	Internal Control Modula, Keep Alive C Memory	Internal Control Module, Memory E check sum
	73 dec hex	$\left \right $	K 84 54	6 55 55	(⁹¹ 58	93 5D	5 7 7	88	97 61	86 28	0 6 10	<u>6</u> 2	101	102 66	103 67
╞	M62 M	$\left \right $			×	×				×		×	× ×	×	×
ŀ	M52	$\left \right $									×				
	M44	ŀ	×	×		×	×	×	×	×			×	×	×
		_				L	L								

DME: MS41.1 (Siemens), M5.2 (Bosch), M5.2.1 (Bosch) Engines: M44, M52, S52, M52ORVR, M62, M62MJ98, M73, M73MJ98

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M44	M52	M62	M73	tex dec	Fault Type and Function	OBD II Requirement / type of test	- Signal Type - Signal Range - Detection of	Input /Output	Explanation	Remark
×		×	×	104	Internal Control Module, RAM	DME HW Test Memory	DME internal Values	DME internally	internal hardware test of RAM, ROM, and Flash Prom.	
		:	;	89			logical			
		×	×	105	M62/M73MY98 only: Internal Control Module, EEPROM	DME HW Test Memory	DME internal Values	DME internally	Internal hardware test of RAM, ROM, and Flash Prom.	
				69			logical			
×		×	×	107	Battery Voltage	Signal Range Check	input analog Batt. Voltage	Battery Voltage	Check that proper battery voltage is present between 9 and 16 Volts. This check is not performed during cranking due to voltage drop.	
				6B			voltage			
×		×	×	108	Battery Voltage Disconnected	Rationality Check	input analog Batt. Voltage	Battery Voltage	ECU internal test determines if the unit has been disconnected from battery cower. This fault could be set by disconnection of the battery or control unit	
				ပ္စ			voltage continuity		or wiring problem effecting B+ supply or ground.	
×		×	×	Ŧ	Crankshaft Position Sensor, Malfunction	Rationality Check	Input digital	Crank sensor	Checks for correct signal pattern and correct number of expected flywheel each	
			:	6F			frequency/pattern			
×		×	×	112	Camshaft Position Sensor Circuit, Malfunction	Rationality Check	input analog 0-5V	Cam sensor	nternal check of the phase shift from the cam sensor which should change Juring every crankshaft revolution. The phase shift occurs due to the 2:1	
				20			phase shift		nechanical relationship between cam and crank.	
×		×	×	115	Mass or Volume Air Flow Circuit, Malfunction	Signal Range Check	Input analog 0-5V	HFM	railed the Signal Range check against predefined diagnostic limits	
				33			voltage			
×		×	×	117	Throttle Position Sensor	Rationality Check	Input analog D-5V	Throttle position	Signal Range is checked against the predetermined diagnostic limits. A ault will set if the Air Flow meter value (volume) does not lonically march.	
				75			voltage		hrottle position sensor value (throttle opening).	
×		×	×	120	Vehicle Speed Sensor	Rationality Check	Input digital	ASC	signal Range is checked against predefined diagnostic limits. No vehicle peed is observed after a specific time when compared to engine speed	
				78			oinary combination		ind load which is equivalent to a moving vehicle.	
×		×	×	121	Load Calculation Cross Check, Bance/Part	Signal Range Check	nput analog	HFM, Throttle	Plausibility check between the Throttle Position Sensor Signal and the	
:		;	;	79			voltage			
×		×	*	123	Engine Coolant Temp, Circuit Banne/Perf	Signal Range Check	nput analog	Coolant Temp	signal Range is checked against the predefined diagnostic limits and the	
:		•	•	78			rotage	Serisor		
×		×	×	124	Intake Air Temperature Range/Performance	Signal Range Check	nput analog 1	ntake Temp.	signal Range is checked against predefined diagnostic limits	
				2		~	oltage			
×		×	×	130	Swapped O2 Sensors Pre Cat.	02 Sensor Check	OME internal Value	02 Sensor	ault will set if the O2 sensor from one bank shows a rich condition while deta ne other bank shows a lean condition.	etailed in
;				82			ogical	<u> </u>		aining

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DME: MS41.1 (Siemens), M5.2 (Bosch), M5.2.1 (Bosch) Engines: M44, M52, S52, M52ORVR, M62, M62MJ98, M73, M73MJ98

M44	t M52	M62	M73	dec tex	Fault Type and Function	OBD II Requirement / type of test	- Signal Type - Signal Range - Detection of	Input /Output	Explanation	Remark
			×	133	M73MY98 only: DME Bank identification input	Rationality Check	input digital on/off	Bank identification-	DME identifies their as a DME_Right or DME_Left depending how the input signal is wired. If it determines that the "learned" value has changed then a fault is detracted.	
				85				pin wiring harness check	הומו מומחוו א המנכרופרי	
×		×	×	135	Transmission: Torque Reduction	Rationality Check	input digital 0-12V	EGS	CAN message had an invalid or undefined value	
				87			binary information			
		*	*	138	AC Compressor Torque Reduction	Timing Check	Input digital	IHKA via K-Bus from the Instr	Checks CAN message for proper content of pulse width modulation signal (>MY97)	
		<	<	8 A			binary information	Cluster		
		>	>	139	Electric Thermostat Control, final	Final stage Check	Output digital	Electric	The final stage inside the DME will set an internal flag whenever a short to pround, a short to battery voltage or a disconnection between the output	
		<	<	88			(active low)		transistor and the connected comp. occurs (0.02A <i<2a).< td=""><td></td></i<2a).<>	
			>	5	M73MY98 only: Torque imbalance	Rationality Check	Input analog	HFM1 and HEM2	Comparison between the 2 air mass signals. If the difference is too large then a fault is detected. Most likely cause is and air leak.	
			<	ပ္စ			voltage	7		
		>	*	141	ASC Signal, Plausibility check	Rationality Check	Input digital 0-12V	ASC	Internal check of binary signals from ASC/MSR/EML. The control unit knows what are the possible combinations of signals. If the combined	
		((80			binary combination		signals don't match the internal table the fault will be set.	
×		×	×	143	MSR Signal	Timing Check	Input digital 0-12V	ASC	Internal check of binary signals from ASC/MSR/EML. The control unit knows what are the possible combinations of signals. If the combined	
:		-	:	8F			binary combination		signals don't match the internal table the fault will be set.	
×		×	×	144	ASC Signal, Plausibility Torque Reduction	Timing Check	Input digital 0-12V	ASC	Internal check of binary signals from ASC/MSR/EML. The control unit rows what are the possible combinations of signals. If the combined sincel control match the internal reheater (on unit has one of the combined sincel control match the internal reheater (on unit has one of the combined to the control match the co	
				8			binary combination			
		×	×	147	Electric Thermostat Control, Range/Performance.	Final stage Check	Output digital on/off	Electric Thermostat	The final stage inside the DME will set an internal flag whenever a short to ground, a short to bathery voltage or a disconnection between the output consistence and the control of construction of the set of the output of the set of the output of the set of the	
				ន			(active low)		וומווטוצותו מות זוים לתוווםתפת תנויה. מכתווס (מיתבאבו-בא).	
×		×	×	148	EWS Signal not present or faulty	DME HW Test SIO	Input binary stream 0-12V	EWS	During the time out check no signal was present within the specific time or faulty information from serial interface (parity, overrun, etc.)	
				8			Bit information			
×	. <u> </u>	×	×	150	Injector Circuit Cylinder 1, Malfunction	Final stage Check	Output digital pulse width (active low)	Injector	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output ransistor and the connected comp. occurs (0.02A <i<2a).< td=""><td></td></i<2a).<>	
				3	Injector Circuit Cylinder 2,	Final stage Check	Output digital	Injector	The final stage inside the DME will set an internal flag whenever a short to	
×		×	×	97	Malfunction		pulse width (active low)		ground, a short to battery voltage or a disconnection between the output iransistor and the connected comp. occurs (0.02Aci<2A).	
				150	Injector Circuit Cylinder 3,	Final stage Check	Output digital	Injector	The final stage inside the DME will set an internal flag whenever a short to	
×		×	×	2 8	Malfunction		pulse width (active low)		ground, a short to bauery vortage or a uscommentari permeent ure output transistor and the connected comp. occurs (0.02A⊲i<2A).	

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Remark													
Explanation	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Aci<2A).	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Aci<2A).</td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A<:<2A).</td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A<i<2a).< td=""><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A<i<2a).< td=""><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A<i≥a).< td=""><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A<i<2a).< td=""><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A<i<2a).< td=""><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Aci<2A).</td><td>The Signal Range is checked to detect shorts on the input line</td><td>The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02A⊲i<2A).</td><td>The final stage inside the DME will set an internal flag wheenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Aci<2A).</td></i<2a).<></td></i<2a).<></td></i≥a).<></td></i<2a).<></td></i<2a).<></td></i<2a).<>	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Aci<2A).	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Input /Output	Injector	Injector	Injector	Injector	Injector	Injector	Injector	Injector	Injector	Fuel pump relay	Tank pressure sensor	Instrument Cluster	Fuel pump relay
Signal Type Signal Range Detection of	Jutput digital sulse width	active low) Jutput digital uulse width active low)	Dutput digital oulse width active low)	Dutput digital bulse width active low)	Dutput digital bulse width active low)	Dutput digital pulse width (active low)	Output digital pulse width (active low)	Output digital pulse width (active low)	Output digital pulse width (active low)	Output digital on/off (active low)	Input analog 0-5V vottage	Dutput digital on/off active low)	Dutput digital an/off active low)
DBD II Requirement /	inal stage Check	inal stage Check	inal stage Check	inal stage Check	inal stage Check (-inal stage Check	Final stage Check	inal stage Check	Final stage Check	Final stage Check	Signal Range Check	-inal stage Check	Final stage Check (
Fault Type and Function	Injector Circuit Cylinder 4, Malfunction	Injector Circuit Cylinder 5, F Malfunction	Injector Circuit Cylinder 6, H Malfunction	Injector Circuit Cylinder 7, Malfunction	Injector Circuit Cylinder 8, Malfunction	Injector Circuit Cylinder 9, Malfunction	Injector Circuit Cylinder 10, Malfunction	Injector Circuit Cylinder 11, Malfunction	Injector Circuit Cylinder 12, Malfunction	M/73M/Y98 only: Electric Fuel Pump Relay, Final stage (Bank 2)	M62M73MY98 only: EVAP: Barometric Tank Pressure Sensor	Check Engine Light, Final stage Malfunction	Electric Fuel Pump Relay, Final stage
T de T	153	98 154 8	155 9B	90 156 90	157 9D	158 9E 19	159 9F	160 A0	161 A1	8 <u>5</u> 8	164 A4	165 A5	167 A7
162 M75	×	×	×	×	×	×	×	×	×	×	×	×	×
≥ 125									<u> </u>				<u> </u>
M44	×	+			<u> </u>	<u> </u>						×	×
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M44	1 W52	W6	2 M73	LÀ ỹ	Eault Type and Function	OBD II Requirement / type of test	- Signal Type - Signal Range - Detection of	Input /Output	Explanation	Remark
L			ļ							
×		×	×	168 A8	Idle Control Valve Opening Coil, Malfunction	Final stage Check	Output digital pulse width (active low)	Idle control valve	The final stage inside the DME will set an internal flag whenever a short to yround, a short to battery voltage or a disconnection between the output ransistor and the connected comp. occurs (0.02A <i<2a).< td=""><td></td></i<2a).<>	
×		×	×	169 A9	Idle Control Valve Closing Coil, Malfunction	Final stage Check	Output digital pulse width (active low)	idle control valve	The final stage inside the DME will set an internal flag whenever a short to pround, a short to battery voltage or a disconnection between the output ransistor and the connected comp. occurs (0.02Aci<2A).	
×		×	×	170 A	AC Compressor Control	Final stage Check	Output digital on/off (active low)	AC Comp.	The final stage inside the DME will set an internal flag whenever a short to pround, a short to battery voltage or a disconnection between the output ansistor and the connected comp. Occurs (0.02Acic2A).	
×		×	×	175 AF	DISA, Range/Performance	Final stage Check	Output digital on/off (active low)	Disa Valve	The final stage inside the DME will set an internal flag whenever a short to pround, a short to batteny voltage or a disconnection between the output ansistor and the connected comp. occurs (0.02A 2A).</td <td></td>	
			×	179 B3	M73MY98 only: AC Compressor Control (Bank 2)	Final stage Check	Output digital on/off (active low)	AC-Control	The final stage inside the DME will set an internal flag whenever a short to pround, a short to battery voltage or a disconnection between the output ransistor and the connected comp. occurs (0.02A <i<da).< td=""><td></td></i<da).<>	
		×	×	183 B7	M62/M73MY98 only: EVAP: Large Leak detected	EVAP Monitoring	Input digital 12V Frequency	LDP reed contact	The frequency of the LDP pumps reed switch is above the predetermined small* leak range. The larger the leak the higher the frequency will be.	detailed in OBD II training
		×	×	184 B8	M62M73MY98 only: EVAP: pinched hose check	EVAP Monitoring	Input digital 12V Frequency	LDP reed contact	The frequency of the LDP pumps reed switch is lower then the redetermined limit. The volume of leak is determined to be too small as 1 a pinched or restricted hose.	detailed in OBD II training
	×			190 190	Only E39MY98: EVAP: Reed Switch not closed	EVAP Monitoring	Input digital 12V Frequency	DP reed	he fault will set if the signal from LDP reed switch is "low" for longer then the predetermined time.	detailed in OBD II training
	×			191 BF	Only E39MY98: EVAP: Reed Switch doesn't open	EVAP Monitoring	Input digital	DP reed	Vithin a predetermined time the LDP reed switch signal has to change om high to low or a fault will set.	detailed in OBD II training
	×			5 <u>5</u> 8	Only E39MY98: EVAP: Reed Switch doesn't close	EVAP Monitoring	Input digital I 12V c on/off	DP reed v contact	within a predetermined time the LDP reed switch signal has to change om high to low or a fault will set.	detailed in OBD II training
	×			5 1 2	Only E39MY98: EVAP: Clamped Tube Check	EVAP Monitoring	Input digital I 12V Frequency	DP reed	he frequency of the LDP pumps reed switch is lower then the redetermined limit. The volume of leak is determined to be too small as in pinched or restricted hose.	detailed in OBD II training
	×			§ 3	Only E39MY98: EVAP: Large Leak detected	EVAP Monitoring	Input digital 12V Frequency	DP reed	he frequency of the LDP purrys reed switch is above the predetermined imall leak range. The larger the leak the higher the frequency will be.	detailed in OBD II training
	×			195 C	Only E33MY98: EVAP: Small Leak detected	EVAP Monitoring	Input digital [L 12V c ⁻ requency	DP reed T	he frequency of the LDP pumps reed switch is above the predetermined mall leak range. The larger the leak the higher the frequency will be.	detailed in OBD II training

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Benc		<u> </u>	edetail mOBD trainir	e detail mOBD trainir	detaik OBD trainir	detaik OBD trainin							
Explanation	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected comp. occurs (0.02Aci<2A).	The Signal Range is checked to detect shorts on the input line	The oxygen sensor signal has to be oscillating under certain normal engine peration conditions. The O2 amplitude signal check must have a minimur of height.	The oxygen sensor signal has to be oscillating under certain normal engine operation conditions. The O2 amplitude signal check must have a minimur of height.	The Controller for Lambda is too long beyond a min. or a max. limit	The Controller for Lambda is too long beyond a min. or a max. limit	Check for correct signal timing after each ignition has been initiated by this ieedback signal	The EWS3.3 rolling code is not stored property in the DME internat nemory	unctional Check between the actual engine speed (FIPM) and the redetermined RPM exceeds the maximum deviation of +200/-100 RPM.	Thecks to see if the O2 sensor reacts to the increase in unmetered air flow enerated by the secondary air pump operation. The O2 sensor must ense the lean condition or a fault will set.	he content of the binary message received from EWS was invalid	faustbility Check between the knock sensor amplitude during knocking rith the internal knock detection mapped DME values.	theck for correct signal timing after each ignition has been initiated by this sedback signal. If more than two ignition is not recognized than there night be a problem in the feedback line itself
Input /Output	LDP	Tank pressure sensor	O2 Sensor	O2 Sensor	Calculated	Calculated	Ignition Shunt Resistor	EWS	calculated	02 Sensor	EWS	Knock sensor	Ignition Shunt Resistor
- Signal Type - Signal Range - Detection of	Output digital on/off (active low)	Input analog 0-5V voltage	Input analog 0-5V (high is lean)	Input analog 0-5V (high is lean)	DME internal Values logical	DME internal Values logical	Input analog 100 mV Timing	DME internal Values	OME internal Values ogical	nput analog 1V vottage	nput binary stream -12V 3it information	nput analog 13-19kHz amplitude	nput analog 00 mV Timing
OBD II Requirement / type of test	Final stage Check	Signal Range Check	02-Sensor Check	02-Sensor Check	Fuel System Monitoring	Fuel System Monitoring I	Ignition Feedback	DME HW-Test	Rationality Check	Secondary Air Delivery II 0 V	Aanipulation Check	Circuit continuity Signal Range Check a	gnition Feedback 11 1
Fault Type and Function	Only E39MY98: EVAP: el. Valve LDP	Orly E39MY98: EVAP: Barometric Pressure Sensor	O2 Sensor Pre Cat. (Bank1), No Activity	02 Sensor Pre Cat. (Bank2) No Activity	Fuel Trim (Bank1), O2 Control Limit	Fuel Trim (Bank2), O2 Control Limit	M62M73MY98 only: Ignition Feedback (bank failed)	M62/M73/MY98 only: rolling code storage	Idle Control System, Idle Speed not I plausible	Secondary Air Induction System ((Bank 2)	EWS Content of Message	Knock Sensor 1 Circuit, (Bank 1) (Ignition Feedback, faulty (>2 l, Cylinders)
E ge Lu	5 26 2	197 C5	ති ස	201 C9	202 C A	203 CB	203 CB	504 C 504	204 CC	208 D0	209 D1	210 D2	210 D2
25 M7:							×	×		×		×	-
ž N							×	×				×	
4 M5	×	×	×	×	×	×			×		×		×
A 4												×	

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	Remar										<u> </u>			-		<u> </u>										
	Explanation		Plausibility Check between the knock sensor amplitude during knocking with the internal knock detection mached DMF values		Functional Check against a calculated value by monitoring the flow though the air mass mater to determine is the intervence is monocontic.	open. Tested during closed throttle deceleration.	Plausibility Check between the knock sensor amplitude during knocking	will the mental knock detection mapped DME values.	Plausibility check between crank and cam sensor signals (timing) before and after the Vanos is switched active.		Plausibility Check between the knock sensor amplitude during knocking with the internal knock detection mapped DME values.	Logical check of every ECU on the CAN bus has a CAN message	interpretation (refer to CAN-Index on the DIS-Tester page) that applies to the vehicle	Signal Range is checked against predefined diagnostic limits. No vehicle stoeed is observed after a streitlic time when compared to around a shoot	and load which is equivalent to a moving vehicle.	Internal check of binary signals from ASC/MSR/EML. The control unit knows what are the possible combinations of signals. If the combined signals don't match the internal table the fault will be set.	The Left DME will check for the Right DME and vice versa. If the CAN message was not received by either within the expected time a fault will	Set.	CAN message had an invalid or undefined value		The CAN message was not received within the expected time		CAN message between DME/EGS was not received within the expected ime		The CAN message was not received within the expected time	
	Input /Output		Knock sensor		calculated		Knock sensor		Crank-/ cam sensor		Knock sensor	Any ECU on	CAN	ASC		ASC	both DMEs		EGS		ASC		EGS		EML ECU	
	- Signal Type - Signal Range - Detection of		Input analog 13-19kHz	amplitude	DME internal Values	togical	Input analog	amplitude	DME internal Values	logical	Input analog 13-19kHz amolitude	input digital	0-12V binary information	Input digital 0-12V	frequency	Input digital 0-12V binary combination	input digital 0-12V	binary information	Input digital 0-12V	oinary information	nput digital	oinary information	nput digital	oinary information	input digital 0-12V	
	OBD II Requirement / type of test		Circuit continuity Signal Range Check	0	Rationality Check		Circuit continuity Signal Banga Chook		Rationality Check		Circuit continuity Signal Range Check	CAN Message Check		Rationality Check		Rationality Check	Timing Check		Rationality Check	Ľ	Timing Check		ME HW Test CAN		Timing Check	
	Fault Type and Function		Knock Sensor 2 Circuit, (Bank 2)		Idle Control Valve stuck		Knock Sensor Signal 3		VANOS mechanically stuck (Bank1)		Knock Sensor Signal 4	M62/M73MY98 only: CAN-Index	Ventication	Vehicle Speed Sensor		ASC/MSR/EML-Interface not plausible	M62/M73MY98 only: CAN-Signal, Timeout Left / Right DME		Gear Selector Signal, Signal		CAN Signal, Timeout ASC		CAN Time Out (EGS1)		M62/M73MY98 only: CAN-Signal, Timeout EML	-
	C B B		211	ß	211	D3	212	2	212	Z	213 DF	214	De	214	g	215 D7	215	6	216	8	216	D8	217	60	217	_
┞	162 M7		×				×				×	'	×				×				×	:			×	_
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	B	smission is		is used to verify control circultry	s used to verify ontrol circuitry	culated DME						detaile OBD II	mever a short to	een the output	detaik	trainin	ich or lean state. detaile	trainin	trainin ich or lean state. detaile OBD I
	Explanation	Hardware test determines if Can Bus is off line. Data tran distributed		The ECU internally generated pulse was not detected. It is electrical integrity (shorts or disconnection) of the knock o both internally and externally.	The ECU internally generated pulse was not detected. It is electrical integrity (shorts or disconnection) of the knock or both internally and externally	Comparison of actual coolant temperature against the calc value which varies with the load signal.)	not applied yet - future enhancement for MY99		not applied yet - future enhancement for MY99	not applied yet - future enhancement for MV99	Range control of adaptation values	The final stage inside the DME will set an internal flag whe	ground, a short to battery voltage or a disconnection betwe transistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>Range control of adaptation values</td><td></td><td>Checks the amount of time the oxygen sensor stays in its rift it remains there too long in either the fault will set.</td><td></td><td>Checks the amount of time the oxygen sensor stays in its rill it remains there too long in either the fault will set.</td></i<2a).<>	Range control of adaptation values		Checks the amount of time the oxygen sensor stays in its rift it remains there too long in either the fault will set.		Checks the amount of time the oxygen sensor stays in its rill it remains there too long in either the fault will set.
	Input /Output	Any ECU on		DME internally	DME Internally	Coolant Temp sensor		EKAT-ECU		EKAT-ECU	EKAT-ECU	Calculated	Starter Relay		Calculated		02 Sensor		O2 Sensor
- Signal Type - Signal Bance	- Detection of	input digital	binary information	DME internal Values logical	DME internal Values	Input analog 0-5V	voltage	input digital 0-12V	binary information	input digital 0-12V binary information	input digital 0-12V binary information	DME internal Values Indical	Output digital	on/off (active low)	DME internal Values	logical	Input analog 0-5V (hich is lean)		Input analog 0-5V
OBD II Requirement /	type of test	DME HW Test CAN		Circuit continuity Signal Range Check	Circuit continuity Signal Range Check	Rationality Check		Electrically heated catalyst check		Electrically heated catalyst check	Electrically heated catalyst check	-uel System Monitoring	Final stage Check		-uel System Monitoring)2-Sensor Check		02-Sensor Check
- - - -	Fault Type and Function	CAN-Chip, Bus Off		Knock control, Test pulse	Knock control, Test pulse (Bank2)	Insufficient Coolant Temp. to permit Closed Loop Operation.		M73LEVMY99 only: EKAT-Status 12 - temperature sensor -	plausibility power switch	M73LEVMY99 only: EKAT-Status 13 temperature sensor - plausibility power switch	M73LEVMY99 only: EKAT-Status 14 - plausibility check of battery disconnection switch	-uel Trim (Bank1), O2 Control	M62/M73MJ98 only: Automatic	Start, Output (Bank 2)	Tuel Trim (Bank2), O2 Control		22 Sensor Pre Cat. (Bank1) Slow (Response time		22 Sensor Pre Cat. (Bank2) Slow C Response time
က ဗိ	hex	219	DB	22 23 23	222	3	DE	225	Ξ	226 E2	227 E3	227 F3	200	E4	228	E4	229 E		530
M73				×	×	ļ		×		×	×			×				ļ	
Me				×	×	ļ								×				L	
M52		×	:			×						×			×		×		×

DME: MS41.1 (Siemens), M5.2 (Bosch), M5.2.1 (Bosch) Engines: M44, M52, S52, M52ORVR, M62, M62MJ98, M73, M73MJ98

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	Explanation		Checks the amount of time the oxygen sensor takes to switch from rich to de lean and vice versa. If it takes too long to switch the fault will set.	tric Compares the value of the of pre cat O2 sensor to value of the post cat O2 de	sensor to measure the oxygen storage capability / efficiency of the catalytic O converter. The post O2 sensor must be relatively lean.	The final stage inside the DME will set an internal flag whenever a short to oround, a short to battery voltane or a disconnection between the output	transistor and the connected comp. occurs (0.02Aci<2A).	Compares the value of the of pre cat O2 sensor to value of the post cat O2 de sensor to measure the oxygen storage capability / efficiency of the catalyric O	converter. The post O2 sensor must be relatively lean.	Fault will set if after a predetermined time with engine revolution is greater than a limit and KI50 still active		Checks the amount of time it takes to heat the O2 sensor to a de predetermined limit as measured by the change in the lean signal. This OI test occurs during deceleration only.	CAN message between DME/EGS was not received within the expected time		Checks the amount of time it takes to heat the O2 sensor to a de predetermined limit as measured by the change in the lean/rich signal. Of This test occurs during deceleration only.	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output transistor and the connected corre. occurs (0.02Asi<2A).	Crankshaft speed/acceleration is monitored by the crank sensor. The time de tor each cylinders combustion is compared against the average of the Others. If the time for cylinder 1 is longer the fault will set.	Use Crankshaft speed/acceleration is monitored by the crank sensor. The time defined action of the crank sensor and the survey of the defined action of the crank senses of the compared actions is compared acting the survey of the crank senses of	others. If the time for cylinder 2 is longer the fault will set.	Crankshaft speed/acceleration is monitored by the crank sensor. The time devious each evaluation is compared arainet the average of the	others. If the time for cylinder31 is longer the fault will set.	Crankshaft speed/acceleration is monitored by the crank sensor. The time det	whers. If the time for cylinder 4 is longer the fault will set
`	Input /Output		O2 Sensor	02 Sensor	pre/post catalyst	Starter Relay		O2 Sensor pre/post catalvst		KL50		O2 Sensor	EGS		O2 Sensor	Starter Relay	Calculated	Calculated		Calculated		Calculated	
	- Signal Type - Signal Range - Detection of		Input analog 0-5V (hich is lean)	Input analog	0-5V voltage	Output digital on/off	(active low)	Input analog D-5V	/oltage	nput digital)-12V	on/off	nternal Shunt Current	nput digital -12V	inary information	Dutput digital nn/off :urrent	Jutput digital m/off active low)	ME internal Values ocical	ME internal Values	ogical	ME internal Values	gical	ME internal Values	aical
	OBD II Requirement / the of test		02-Sensor Check	Catalyst Monitoring		-inal stage Check		Catalyst Monitoring		tationality Check		2-Sensor Check	ME HW Test CAN		2-Sensor Check 0	inal stage Check	lisfire Monitoring	isfire Monitoring	<u>k</u>	isfire Monitoring	<u> </u>	isfire Monitoring	<u></u>
	Fault Type and Function		UZ-Sensor Pre Cat (Bank 2), Switching time too slow	Catalyst Efficiency Bank 1, Below (M62/M73MJ98 only: Automatic Start, Output		Catalyst Efficiency Bank 2, Below (Threshold		Automatic Start, input		OZ-Sensor-Heater, Post Cat. (Bank1), Insufficient Heating.	CAN Time Out (EGS)		02-Sensor-Heater, Post Cat. (Bank2), Insufficient Heating.	Automatic Start, Output	Cylinder 1 Misfire detected	Cylinder 2 Misfire detected M		Cylinder 3 Misfire detected		Oylinder 4 Misfire detected M	
	73 dec Ta	$\left \right $	232 E8	233	£	(233	B	234	Ð	234	₹	235 EB	536	<u></u>	236 EC	237 ED	238 EE	239	Ш	240	8	241	Ē
╞	M62 M	$\left \right $		╞	_	×			╉	× ×	+		× ×	+		×			-				
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	Remark	detailed in	OBD II training	detailed in	OBD II training	detailed in	training					detailed in OBD II	training	detailed in OBD II	training	detailed in OBD II	training	detailed in OBD II	training			detailed in OBD II	training	detailed in OBD II	training
	Explanation	Crankshaft speed/acceleration is monitored by the crank sensor. The time	for each cylinders combustion is compared against the average of the others. If the time for cylinder 5 is longer the fault will set.	Crankshaft speed/acceleration is monitored by the crank sensor. The time	ror each cymroers compusion is compared against the average of the others. If the time for cylinder 6 is longer the fault will set.	The flywheel segmentsare monitored during deceleration to establish a baseline for misfire calculation. If the segments are too lond/short (bad	flywheel) and exceed the limit a fault will set or one tooth too much/less.	Checks to see if the O2 sensor reacts to the increase in unmetered airflow openerated by the secondary air pump operation. The O2 sensor must	sense the lean condition of a fault will set.	Checks to see if the O2 sensor reacts to the increase in unmetered airflow generated by the secondary air pump operation. The O2 sensor must	sense the lean condition or a fault will set.	This functional check looks for the reaction of the O2 sensor signal during canister purging. The O2 sensor, Air Flow meter and RPM values must	react to the purging of the canister	With the purge and shut off valves closed the gas tank is introduced to intake manifold vacuum. The tank pressure sensor looks for a	predetermined pressure (vacuum) difference within a specific time.	During purging with the open TEV valve the tank pressure sensor must react to the decrease in pressure. It must reach a minimum pressure	differential after a predetermined time or a fault will set	The signal from the Tank pressure sensor determines that the tank has a pressure lower (higher vacuum) than the predetermined value. This fault k	will occur if the Shut off Valve is stuck closed or restricted.	The final stage inside the DME will set an internal flag whenever a short to ground, a short to battery voltage or a disconnection between the output	transistor and the connected comp. occurs (0.02A <i<2a).< td=""><td>During purging with the open TEV valve the tank pressure sensor must react to the decrease in pressure. It must reach a minimum pressure</td><td>differential after a predetermined time or a fault will set</td><td>Check for HC in canister with vehicle speed equal to zero, purge and b shutoff valves closed the tank pressure after a predetermined time must be k</td><td>greater than the pressure observed during engine start</td></i<2a).<>	During purging with the open TEV valve the tank pressure sensor must react to the decrease in pressure. It must reach a minimum pressure	differential after a predetermined time or a fault will set	Check for HC in canister with vehicle speed equal to zero, purge and b shutoff valves closed the tank pressure after a predetermined time must be k	greater than the pressure observed during engine start
	Input /Output	Calculated		Calculated		Crank sensor		O2-Sensor signal		O2-Sensor signal	1	O2 Sensor Signal)	Tank pressure sensor		Tank pressure sensor		Tank pressure sensor		Coolant Fan		Tank pressure sensor		purge valve	
	- Signal Type - Signal Range - Detection of	DME internal Values	logical	DME internal Values	logical	Input digital 0-12V	timing	Input analog D-5V	voltage	Input analog D-5V	voltage	Input analog D-5V	/oltage	nput analog)-5V	/oltage	nput analog)-5V	/oltage	nput analog)-5V	/oltage	Dutput digital pulse width	active low)	nput analog)-5V	ottage	nput analog)-5V	ottace
	OBD II Requirement / type of test	Misfire Monitoring		Misfire Monitoring		Rationality Check		Secondary Air Delivery		Secondary Air Delivery		EVAP Monitoring		EVAP Monitoring		EVAP Monitoring		EVAP Monitoring		inal stage Check		EVAP Monitoring	~	EVAP Monitoring	_
	Fault Type and Function	Ovlinder 5 Misfire detected		Cylinder 6 Misfire detected		Segment Timing faulty- Flywheel		Secondary Air Injection (Bank1),Flow too Low		Secondary Air Injection (Bank2),Flow too Low		EVAP System, TEV		EVAP System, Leak Detected (small leak)		EVAP System, Incorrect Purge Flow		EVAP System, Shut Off Valve Stuckle closed		Coolant Fan, Final stage		EVAP System, Leak Detected (large E leak)		EVAP System, TEV Stuck Open	
	M73 de F	245	2	243	£	244	F4	245	55	246	F6	250	FA	251	B	252	Б	253	£	X 253	8	254	Ë	255	Ľ
-	M62																			×					
M52			,	<	×		×		×		×		×		×		×				×		×		
	M44																		×					_	

Α

Alternate or Equivalent Phase-in: Phase in of equivalent emission reductions by the end of the last year of the scheduled phase-in.

The emission reductions are calculated by multiplying the percent of vehicles (based on the manufacturer's projected sales volume of all vehicles and engines) meeting the new requirements per year by the number of years implemented prior to and including the last year of the scheduled phase-in and then summing these yearly results to determine a cumulative total.

Β

Base Fuel Schedule: refers to the fuel calibration schedule programmed into the Powertrain Control Module or PROM when manufactured or when updated by some off-board source, prior to any learned on-board correction.

С

Catalyst Monitoring:

Non-Low Emission Vehicles: The catalyst system shall be considered malfunctioning when its conversion capability decreases to the point that HC emissions increase by more than 1.5 times the standard over an FTP test from a test run with a representative 4000 mile catalyst system.

Transitional Low Emission Vehicles TLEV: these vehicles shall employ an emission threshold malfunction criterion of 2.0 times the applicable FTP HC standard plus the emissions from a test run with a representative 4000 mile catalyst system.

Low Emission Vehicles LEV: The catalyst system shall be considered malfunctioning when its conversion capability decreases to the point that either of the following occurs:

1. Hydrocarbon (HC) emissions exceed the applicable emission threshold specified. The emission threshold criterion for LEV and ULEV applications shall be 2.5 and 3.0 times the applicable FTP HC standard, respectively, plus the emission level with a representative 4000 mile catalyst system. Notwithstanding, beginning with the 1998 model year, manufacturers shall phase in an emission threshold of 1.75 times the applicable FTP HC standard for all categories of low emission vehicles, which shall not include the emission level with a 4000 mile catalyst system.

2. The average Federal Test Procedure (FTP) Non-Methane Hydrocarbon (NMHC) conversion efficiency of the monitored portion of the catalyst system falls below 50 percent.

С

CARB- California Air Resources Board: The California Air Resources Board mission is to promote and protect public health, welfare and ecological resources through the effective and efficient reduction of air pollutants while recognizing and considering the effects on the economy of the state of California.

California's Legislature established the Air Resources Board (ARB) in 1967 to:

- 1. Attain and maintain healthy air quality.
- 2. Conduct research into the causes of and solutions to air pollution.

3. Systematically attack the serious problem caused by motor vehicles, which are the major causes of air pollution in the state.

Since its formation, the ARB has worked with the public, the business sector, and local governments to protect the public's health, the economy, and the state's ecological resources through the most cost-effective reduction of air pollution.

What the ARB Does: Programs for cleaner air range from research and regulation to enforcement and education. The ARB:

- 1. Sets and enforces emission standards for motor vehicles , fuels, and consumer products
- 2. Sets health-based air quality standards
- 3. Conducts research
- 4. Monitors air quality
- 5. Identifies and sets control measures for toxic air contaminants
- 6. Provides compliance assistance for businesses
- 7. Produces education and outreach programs and materials

8. Oversees and assists local air quality districts which regulate most non-vehicular sources of air pollution.

For extensive information on the CARB, visit their website at = http://www.arb.ca.gov

Continuous monitoring: means sampling at a rate no less than two samples per second. If for engine control purposes, a computer input component is sampled less frequently, the value of the component may instead be evaluated each time sampling occurs.

"CLV" Calculated load value: A formula that refers to an indication of the current airflow divided by peak airflow, where peak airflow is corrected for altitude, if available. This definition provides a unitless number that is not engine specific, and provides the service technician with an indication of the percent engine capacity that is being used (with wide open throttle as 100%).



D

Diagnostic Link Connector (DLC): SAE standardized aftermarket scantool-vehicle interface connector. Located in the interior of the vehicle.

Drive or Driving Cycle: consists of engine startup, vehicle operation and engine shutoff.

Diagnostic Trouble Code (DTC): SAE standardized OBD-II fault code. This code structure is designed by the SAE to identify identical faults along all vehicle manufacture systems. These fault codes are accessed by using an aftermarket scantool via the DLC. If using the BMW DIS or MoDiC, these fault codes provide no additional information already provided by the BMW diagnostic equipment.

Ε

Engine misfire: means lack of combustion in the cylinder due to absence of spark, poor fuel metering, poor compression, or any other cause.

Engine Start: is defined as the point at which normal, synchronized spark and fuel control is obtained or when the engine reaches a speed 150 rpm below the normal, warmed-up idle speed (as determined in the drive position for vehicles equipped with an automatic transmission).

Evaporative System Monitoring:

The system is considered to be malfunctioning when:

- No purge air flow can be detected (Oxygen Sensor Feedback), or
- When a leak is detected in the system that is equal to or larger than 1mm (0.040 in.).

F

Federal Test Procedure (FTP): a specific driving cycle that is utilized by the EPA to test light duty vehicles and light duty truck emissions. As part of the procedure for a vehicle manufacturer to obtain emission certification for a particular model/engine family the manufacturer must demonstrate that the vehicle(s) can pass the FTP defined driving cycle two consecutive times while monitoring various components/systems.

Some of the components/systems must be monitored either once per driving cycle or continuously.

Components/systems required to be monitored once within one driving cycle:

- Oxygen Sensors
- Secondary Air Injection System
- Catalyst Efficiency
- Evaporative Vapor Recovery System

Components/systems required to be monitored continuously:

- Misfire detection
- Fuel system
- Oxygen Sensors
- All emissions related systems providing or receiving signals to the DME, EGS, or EML.

NOTE: Due to the complexity involved in meeting the test criteria within the FTP defined driving cycle, all tests may not be completed within one "customer driving cycle". The test can be successfully completed within the FTP defined criteria, however customer driving styles may differ and therefore may not always monitor all involved components/systems in one "trip".



Fuel trim: refers to feedback adjustments to the base fuel schedule. Short-term fuel trim refers to dynamic or instantaneous adjustments. Long-term fuel trim refers to much more gradual adjustments to the fuel calibration schedule than short-term trim adjustments. These long term adjustments compensate for vehicle differences and gradual changes that occur over time.

Functional check: for an output component means verification of proper response to a computer command. For an input component, functional check means verification of the input signal being in the range of normal operation, including evaluation of the signals

G

Η	
J	

J-Specifications: The SAE established the required specifications for the EPA/ARB OBD II program. These are known as the J specs. By visiting the SAE website @ www.sae.org, detailed information regarding the following specs can be accessed.

SAE J1930 - Standardization of system terms, definitions abbreviations and acronyms. SAE J1962 - Diagnostic Link Connector pin assignments and manufacturing dimensions. SAE J2012 - Definitions of Diagnostic Trouble Codes (DTCs)

There are additional J specifications related to the On Board Diagnostics Program which can be obtained by purchasing the SAE <u>On Board Diagnostics for Light and Medium Duty Vehicles Standards Manual</u> via the SAE website.

K

Low Emission Vehicle: refers to a vehicle certified in California as a Transitional Low Emission Vehicle (TLEV), a Low Emission Vehicle (LEV), or an Ultra Low Emission Vehicle (ULEV). These vehicle categories are further defined in Title 13, sections 1956.8 and 1960.1.

Μ

Malfunction: means the inability of an emission-related component or system to remain within design specifications.

Further, malfunction refers to the deterioration of any emission related components or system to a degree that would likely cause the emissions of an average certification durability vehicle with the deteriorated components or systems present at the beginning of the applicable certification emission test to exceed by more than 1.5 times any of the emission standards.

Misfire: means lack of combustion in the cylinder due to absence of spark, poor fuel metering, poor compression, *or any other cause.*

Misfire Monitoring: The diagnostic system shall monitor engine misfire and shall identify the specific cylinder experiencing misfire via MIL activation and fault code. If more than one cylinder is misfiring, a separate code shall indicate that multiple cylinders are misfiring plus specifying the individual misfiring cylinders.

0

On-Board Diagnostics: On-Board Diagnostic (OBD) systems are incorporated into the emission related control modules (DME, EGS/AGS/EML) in new vehicles to monitor components and systems that affect emissions when malfunctioning.

California's second generation of OBD requirements (known as OBD II) have been fully in effect since the 1996 model year. OBD II systems monitor virtually every component that can affect the emission performance of the vehicle. If a problem is detected, the OBD II system illuminates a warning lamp on the vehicle instrument panel to alert the driver. This warning lamp typically contains the phrase Check Engine or Service Engine Soon. The system will also store important information about the detected malfunction so that a repair technician can accurately find and fix the problem.

Oxygen sensor "response rate": refers to the delay (measured in milliseconds) between a switch of the sensor from lean to rich or vice versa in response to a change in fuel/air ratio above and below stoichiometric.

Ρ

P-Codes: See Diagnostic Trouble Codes

Q-R

Redline engine speed: means the manufacturer recommended maximum engine speed as normally displayed on instrument panel tachometers, or the engine speed at which fuel shutoff occurs.

S

Secondary air: refers to air introduced into the exhaust system by means of a pump or aspirator valve or other means that is intended to aid in the oxidation of HC and CO contained in the exhaust gas stream.

Small volume manufacturer: any vehicle manufacturer with sales less than or equal to 3000 new light-duty vehicles and medium-duty vehicles per model year based on the average number of vehicles sold by the manufacturer each model year from 1989 to 1991, except as follows;

For manufacturers certifying for the first time in California, model year sales shall be based on projected California sales. If a manufacturer's average California sales exceeds 3000 units of new light-duty and medium-duty vehicles based on the average number of vehicles sold for any three consecutive model years, the manufacturer shall no longer be treated as a small volume manufacturer and shall comply with the requirements applicable for larger manufacturers beginning with the fourth model year after the last of the three consecutive model years.

If a manufacturer's average California sales falls below 3000 units of new light-duty and medium-duty vehicles based on the average number of vehicles sold for any three consecutive model years, the manufacturer shall be treated as a small volume manufacturer and shall be subject to the requirements for small volume manufacturers beginning with the next model year.

Т

Trip: means vehicle operation (following an engine-off period) long enough that all components and systems are monitored at least once by the diagnostic system. Catalyst efficiency and/or evaporative system monitoring does not necessarily have to occur when a steadyspeed check is used. This is subject to the limitation that the manufacturer-defined trip monitoring conditions shall all be encountered at least once during the first engine start portion of the applicable FTP cycle.

U-V

Unified Cycle: is defined in "Speed Versus Time Data for California's Unified Driving Cycle", dated December 12, 1996, incorporated by reference.

W-X

Warm-up cycle: means sufficient vehicle operation such that the coolant temperature has risen by at least 40 degrees Fahrenheit from engine starting and reaches a minimum temperature of at least 160 degrees Fahrenheit (140 degrees Fahrenheit for diesel applications).

Y-Z